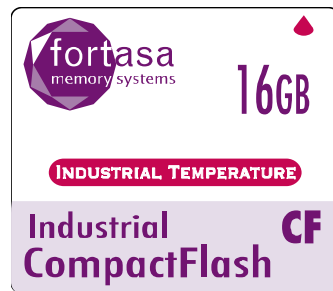
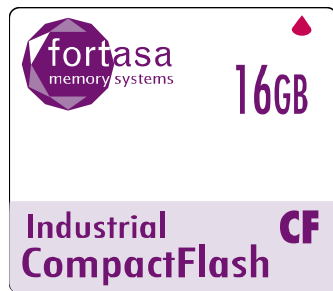


RoHS Compliant
Industrial CompactFlash Series
August 11, 2013
Revision 1.1



***This Specification Describes the Features and Capabilities of
the Standard and Industrial Temperature
CompactFlash Cards***

***Please Contact Fortasa Sales for any Custom Features
Required For Your Specific Application***



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2nd Floor
Palo Alto, CA 94303 USA
888-367-8588
www.fortasa.com

Features:

- **CompactFlash Association Specification Revision 3.0 Standard Interface**

- ATA command set compatible
 - ATA mode support for up to:
 - PIO Mode-6
 - Multiword DMA Mode-4
 - Ultra DMA Mode-4

- **Connector Type**

- 50 pins female

- **Low power consumption (typical)**

- Supply voltage: 3.3V & 5V
- Active mode: 80 mA/95 mA (3.3V/5.0V)
- Sleep mode: 700 μ A/900 μ A (3.3V/5.0V)

- **Performance**

- Sustained read: up to 29 MB/sec
- Sustained write: up to 15 MB/sec

- **Capacity**

- 128, 256, 512 MB
- 1, 2, 4, 8, 16GB

- **NAND flash type: SLC**

- **Superior Reliability Through Built-in Hardware ECC**

- Corrects up to 8 random single-bit errors per 512-byte sector

- **Endurance in Terrabytes Written (TBW)**

- 128 MB: 3.3 TBW
- 256 MB: 6.7 TBW
- 512 MB: 12.9 TBW
- 1 GB: 25.6 TBW
- 2 GB: 38.4 TBW
- 4 GB: 51.9 TBW
- 8 GB: 69.8 TBW
- 16 GB: 115.0 TBW

- **Temperature ranges**

- Operation:
 - Standard Temperature: 0 °C to 70 °C
 - Industrial Temperature: -40 °C to 85 °C
- Storage: -40 °C to 100 °C

- **Flash management**

- Intelligent endurance design
 - Advanced wear-leveling algorithms*
 - S.M.A.R.T. Technology*
 - Enhanced Data Integrity*
- Intelligent power failure recovery

- **RoHS compliant**

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1. General Description

Fortasa's Industrial CompactFlash Card (CFC) offers the highest reliability and performance storage solution critical to most demanding OEM customers. Unlike off-the-shelf consumer CompactFlash cards, Fortasa's Industrial CompactFlash card offers superior manufacturing quality and component traceability to ensure all that product shipments match that of a qualified product.

Fortasa's CFC provides complete PCMCIA - ATA functionality and compatibility. Fortasa's CompactFlash technology is designed for use in Point of Sale (POS) terminals, telecom, IP-STB, medical instruments, surveillance systems, industrial PCs and handheld applications. Featuring advanced technologies such as Advanced Wear-leveling algorithms, S.M.A.R.T, Enhanced Data Integrity, Built-in Hardware ECC, and Intelligent Power Failure Recovery, Fortasa's Industrial CompactFlash Card offers the most reliable storage solution for most critical applications.

Offered in both standard and industrial temperature ranges, Fortasa's Industrial CompactFlash product should be the most trustworthy solution in the OEM memory system.

2. Functional Block

The CompactFlash Card (CFC) includes a controller and flash media, as well as the CompactFlash standard interface. Figure 2-1 shows the functional block diagram.

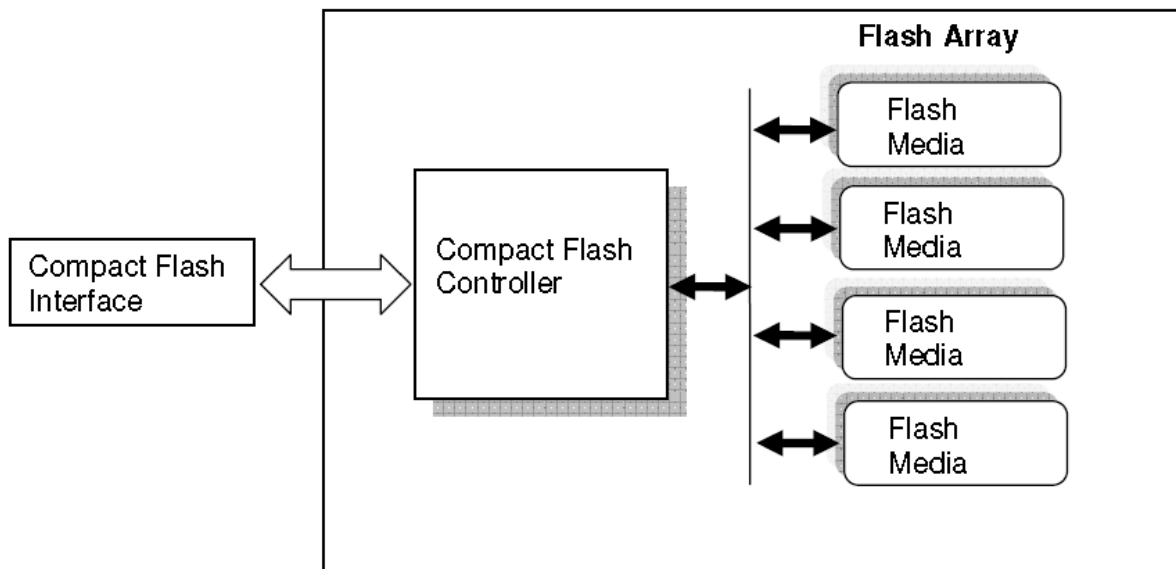


Figure 2-1 – Block Diagram

3. Pin Assignments

Table 3-1 lists the pin assignments with respective signal names for the 50-pin configuration. A “#” suffix indicates the active low signal. The pin type can be input, output or input/output.

Table 3-1: Pin assignments (1 of 2)

| Pin No. | Memory card mode | | I/O card mode | | True IDE mode | |
|---------|------------------|--------------|---------------|--------------|------------------|--------------|
| | Signal name | Pin I/O type | Signal name | Pin I/O type | Signal name | Pin I/O type |
| 1 | GND | - | GND | - | GND | - |
| 2 | D3 | I/O | D3 | I/O | D3 | I/O |
| 3 | D4 | I/O | D4 | I/O | D4 | I/O |
| 4 | D5 | I/O | D5 | I/O | D5 | I/O |
| 5 | D6 | I/O | D6 | I/O | D6 | I/O |
| 6 | D7 | I/O | D7 | I/O | D7 | I/O |
| 7 | #CE1 | I | #CE1 | I | #CE1 | I |
| 8 | A10 | I | A10 | I | A10 ¹ | I |
| 9 | #OE | I | #OE | I | #OE | I |
| 10 | A9 | I | A9 | I | A9 ¹ | I |
| 11 | A8 | I | A8 | I | A8 ¹ | I |
| 12 | A7 | I | A7 | I | A7 ¹ | I |
| 13 | VCC | - | VCC | - | VCC | - |
| 14 | A6 | I | A6 | I | A6 ¹ | I |
| 15 | A5 | I | A5 | I | A5 ¹ | I |
| 16 | A4 | I | A4 | I | A4 ¹ | I |
| 17 | A3 | I | A3 | I | A3 ¹ | I |
| 18 | A2 | I | A2 | I | A2 | I |
| 19 | A1 | I | A1 | I | A1 | I |
| 20 | A0 | I | A0 | I | A0 | I |
| 21 | D0 | I/O | D0 | I/O | D0 | I/O |
| 22 | D1 | I/O | D1 | I/O | D1 | I/O |
| 23 | D2 | I/O | D2 | I/O | D2 | I/O |
| 24 | WP | O | #IOCS16 | O | #IOCS16 | O |
| 25 | #CD2 | O | #CD2 | O | #CD2 | O |
| 26 | #CD1 | O | #CD1 | O | #CD1 | O |
| 27 | D11 | I/O | D11 | I/O | D11 | I/O |
| 28 | D12 | I/O | D12 | I/O | D12 | I/O |
| 29 | D13 | I/O | D13 | I/O | D13 | I/O |
| 30 | D14 | I/O | D14 | I/O | D14 | I/O |
| 31 | D15 | I/O | D15 | I/O | D15 | I/O |
| 32 | #CE2 | I | #CE2 | I | #CE2 | I |
| 33 | #VS1 | O | #VS1 | O | #VS1 | O |
| 34 | #IOR | I | #IOR | I | #IOR | I |
| 35 | #IOWR | I | #IOWR | I | #IOWR | I |
| 36 | #WE | I | #WE | I | #WE | I |
| 37 | RDY-BSY | O | -IREQ | O | INTRQ | O |
| 38 | VCC | - | VCC | - | VCC | - |
| 39 | #CSEL | I | #CSEL | I | #CSEL | I |
| 40 | #VS2 | O | #VS2 | O | #VS2 | O |
| 41 | RESET | I | RESET | I | RESET | I |

Table 3-1: Pin assignments (2 of 2)

| Pin No. | Memory card mode | | I/O card mode | | True IDE mode | |
|---------|------------------|--------------|---------------|--------------|--------------------|--------------|
| | Signal name | Pin I/O type | Signal name | Pin I/O type | Signal name | Pin I/O type |
| 42 | #WAIT | O | #WAIT | O | ICRDY | O |
| 43 | #INPACK | O | #INPACK | O | DMARQ ² | O |
| 44 | -REG | I | #REG | I | DMACK ² | I |
| 45 | BVD2 | O | #SPKR | O | #DASP | I/O |
| 46 | BVD1 | O | #STSC HG | O | #PDIAG | I/O |
| 47 | D8 | I/O | D8 | I/O | D8 | I/O |
| 48 | D9 | I/O | D9 | I/O | D9 | I/O |
| 49 | D10 | I/O | D10 | I/O | D10 | I/O |
| 50 | GND | - | GND | - | GND | - |

1. The signal should be tied to VCC by the host.
2. Connection required when UDMA is in use.

4. Capacity Specification

Standard capacity specification of the CompactFlash Card products are shown in Table 4-1. The table lists the specific capacity and the default numbers of heads, sectors and cylinders (CHS) for each product line.

Table 4-1: Capacity specifications

| Capacity | Total Bytes ^{1,2} | Cylinders | Heads | Sectors | Max LBA |
|----------|----------------------------|--------------------|-------|---------|------------|
| 128MB | 128,450,560 | 980 | 8 | 32 | 250,880 |
| 256MB | 256,901,120 | 980 | 16 | 32 | 501,760 |
| 512MB | 512,483,328 | 993 | 16 | 63 | 1,000,944 |
| 1GB | 1,024,966,656 | 1,986 | 16 | 63 | 2,001,888 |
| 2GB | 2,048,901,120 | 3,970 | 16 | 63 | 4,001,760 |
| 4GB | 4,110,188,544 | 7,964 | 16 | 63 | 8,027,712 |
| 8GB | 8,195,604,480 | 15,880 | 16 | 63 | 16,007,040 |
| 16GB | 16,391,208,960 | 16383 ³ | 16 | 63 | 32,014,080 |

1. Total bytes includes reserved system blocks.
2. Total bytes displayed varies depending on the operating system.
3. Cylinders, heads or sectors are not applicable for these capacities. Only LBA addressing applies.

Please contact Fortasa Memory Systems Sales for any non-listed CompactFlash Card capacity or custom CHS requirement.

4.1 Performance Specification

Performances of the CompactFlash Card is listed in Table 4-2.

Table 4-2: Performance specifications

| Capacity \ Performance | 128MB | 256MB | 512MB | 1GB | 2GB | 4GB | 8GB | 16GB |
|------------------------|-------|-------|-------|-----|-----|-----|-----|------|
| Sustained read (MB/s) | 17 | 29 | 19 | 21 | 20 | 21 | 21 | 20 |
| Sustained write (MB/s) | 4 | 8 | 7 | 12 | 11 | 11 | 13 | 15 |

4.2 Environmental Specifications

Environmental specification of the CompactFlash Card series follows the MIL-STD-810F standard as shown in Table 4-3.

Table 4-3: Environmental specifications

| Environment | | Specification |
|-------------|-----------|--|
| Temperature | Operation | 0°C to 70°C (standard); -40°C to 85°C (Industrial temperature) |
| | Storage | -40°C to 100°C |
| Vibration | | Sine wave: 10~2000Hz, 15G (X, Y, Z axes) |
| Shock | | Half sine wave, Peak acceleration 50 G, 11 ms (X, Y, Z ; All 6 axes) |
| Humidity | | 5% to 95% RH (Non-condensing) |

4.3 Endurance

The endurance of a storage device is predicted by a JEDEC approved test methodology. The data, reported in TeraBytes Written, is based on several factors related to device architecture and product usage, such as the amount of data written into the drive, block management conditions, and daily workload for the drive. Please contact Sales to learn more about the TBW analysis and calculations.

| Capacity | TBW |
|----------|-------|
| 128MB | 3.3 |
| 256MB | 6.7 |
| 512MB | 12.9 |
| 1GB | 25.6 |
| 2GB | 38.4 |
| 4GB | 51.9 |
| 8GB | 69.8 |
| 16GB | 115.0 |

Notes:

- The measurement assumes the data written to the SSD for test is under a typical and constant rate.
- The measurement follows the standard metric: 1 TB (Terabyte) = 1000 GB.

5. Flash Management

The most critical attribute of an Industrial grade CompactFlash Card is its inherent high level of reliability. This characteristic is achieved through unique technical features of Flash Controller and specific component selection that offer higher degree of reliability compared to the consumer grade components.

5.1 Intelligent Flash Controller Features

5.1.1 Advanced wear-leveling algorithms

All NAND flash devices are limited by a finite number of write cycles. Under a standard file system, frequent file table updates are mandatory. As a painful side effect of OS file overhead, some areas of flash address space wear out faster than others. As these certain sections get a substantially higher write occurrence the whole CompactFlash card can wear out very quickly. This uneven wear would significantly reduce the lifetime of the whole device, even if majority of the Flash sectors are far from the write cycle limit. Fortasa's CompactFlash Card products offer advanced data wear leveling which distributes Flash writes evenly across the card memory space. By utilizing this advanced wear leveling feature, the lifetime of the media can be significantly extended.

5.1.2 S.M.A.R.T. technology

S.M.A.R.T. is an acronym for Self-Monitoring, Analysis and Reporting Technology, an open standard allowing disk drives to automatically monitor their own health and report potential problems. It protects the user from unscheduled downtime by monitoring and storing critical drive performance and calibration parameters. Ideally, this should allow taking proactive actions to prevent impending drive failure. Fortasa SMART feature adopts the conventional SMART command B0h to read data from the drive. By having the Fortasa SMART Utility running on the host, the system can monitor and analyze the CompactFlash card status and determine the end of useful life for a graceful and scheduled maintenance and replacement.

5.1.3 Built-in hardware ECC

The Fortasa Flash Controller uses superior BCH Error Detection Code (EDC) and Error Correction Code (ECC) algorithms which correct up to eight random single-bit errors for each 512-byte block of data. High performance is fulfilled through hardware-based error detection and correction.

5.1.4 Enhanced data integrity

The properties of NAND flash memory make it ideal for applications that require high integrity while operating in challenging environments. The integrity of data to NAND flash memory is generally maintained through ECC algorithms and bad block management. Flash controllers can support up to 8 bits ECC capability for accuracy of data transactions, and bad block management is a preventive mechanism from loss of data by retiring unusable media blocks and relocating the data to the other blocks, along with the integration of advanced wear leveling algorithms, so that the lifespan of device can be expanded.

5.2 Intelligent Power Failure Recovery

The Low Power Detection on the Flash controller initiates cached data saving before the power supply to the device drops too low for operation. This feature prevents the device from system crash and ensures data integrity during an unexpected brownout. This feature makes sure that there are no catastrophic failures of the CompactFlash due to system power glitches.

6. Software Interface

6.1 Command Set

Table 6-1 summarizes the command set with the paragraphs that follow describing the individual commands and the task file for each.

Table 6-1: Command set

| Command | Code | FR ¹ | SC ² | SN ³ | CY ⁴ | DH ⁵ | LBA ⁶ |
|-------------------------------|------------|-----------------|-----------------|-----------------|-----------------|-----------------|------------------|
| Check-Power-Mode | E5H or 98H | - | - | - | - | D8 | - |
| Execute-Drive-Diagnostic | 90H | - | - | - | - | D | - |
| Erase-Sector(s) | C0H | - | Y | Y | Y | Y | Y |
| Flush-Cache | E7H | - | - | - | - | D | - |
| Format-Track | 50H | - | Y ⁷ | - | Y | Y ⁸ | Y |
| Identify-Drive | ECH | - | - | - | - | D | - |
| Idle | E3H or 97H | - | Y | - | - | D | - |
| Idle-Immediate | E1H or 95H | - | - | - | - | D | - |
| Initialize-Drive-Parameters | 91H | - | Y | - | - | Y | - |
| NOP | 00H | - | - | - | - | D | - |
| Read-Buffer | E4H | - | - | - | - | D | - |
| Read DMA | C8H or C9H | - | Y | Y | Y | Y | Y |
| Read-Long-Sector | 22H or 23H | - | - | Y | Y | Y | Y |
| Read-Multiple | C4H | - | Y | Y | Y | Y | Y |
| Read-Sector(s) | 20H or 21H | - | Y | Y | Y | Y | Y |
| Read-Verify-Sector(s) | 40H or 41H | - | Y | Y | Y | Y | Y |
| Recalibrate | 1XH | - | - | - | - | D | - |
| Seek | 7XH | - | - | Y | Y | Y | Y |
| Set-Features | EFH | Y | - | - | - | D | - |
| SMART | B0H | Y | Y | Y | Y | D | - |
| Set-Multiple-Mode | C6H | - | Y | - | - | D | - |
| Set-Sleep-Mode | E6H or 99H | - | - | - | - | D | - |
| Set-WP_PD#-Mode | 8BH | Y | - | - | - | D | - |
| Stand-By | E2H or 96H | - | - | - | - | D | - |
| Stand-By-Immediate | E0H or 94H | - | - | - | - | D | - |
| Translate Sector | 87H | - | Y | Y | Y | Y | Y |
| Write-Buffer | E8H | - | - | - | - | D | - |
| Write DMA | CAH or CBH | - | Y | Y | Y | Y | Y |
| Write-Long-Sector | 32H or 33H | - | - | Y | Y | Y | Y |
| Write-Multiple | C5H | - | Y | Y | Y | Y | Y |
| Write-Multiple-Without-Erase | CDH | - | Y | Y | Y | Y | Y |
| Write-Sector(s) | 30H or 31H | - | Y | Y | Y | Y | Y |
| Write-Sector(s)-Without-Erase | 38H | - | Y | Y | Y | Y | Y |
| Write-Verify | 3CH | - | Y | Y | Y | Y | Y |

1. FR - Features register

2. SC - Sector Count register

3. SN - Sector Number register

4. CY - Cylinder registers

5. DH - Drive/Head register

6. LBA - Logical Block Address mode supported (see command descriptions for use)

7. Y - The register contains a valid parameter for this command

8. For the Drive/Head register:

Y means both the CFC and Head parameters are used

D means only the CFC parameter is valid and not the Head parameter

6.1.1 Check-Power-Mode - E5H or 98H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|------------|---|---|-------|---|---|---|---|
| Command (7) | 98H or E5H | | | | | | | |
| C/D/H (6) | X | | | Drive | X | | | |
| Cyl High (5) | | | | | X | | | |
| Cyl Low (4) | | | | | X | | | |
| Sec Num (3) | | | | | X | | | |
| Sec Cnt (2) | | | | | X | | | |
| Feature (1) | | | | | X | | | |

This command checks the power mode. Because the CompactFlash card can recover from sleep in 200 ns, idle mode is never enabled. The CompactFlash card sets BSY, sets the Sector Count register to 00H, clears BSY and generates an interrupt.

6.1.2 Execute-Drive-Diagnostic - 90H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|-----|---|---|-------|---|---|---|---|
| Command (7) | 90H | | | | | | | |
| C/D/H (6) | X | | | Drive | X | | | |
| Cyl High (5) | | | | | X | | | |
| Cyl Low (4) | | | | | X | | | |
| Sec Num (3) | | | | | X | | | |
| Sec Cnt (2) | | | | | X | | | |
| Feature (1) | | | | | X | | | |

This command performs the internal diagnostic tests implemented by the CompactFlash card. If the Drive bit is ignored and the diagnostic command is executed by both the Master and the Slave with the Master responding with status for both devices, the Diagnostic codes shown in Table 6-2 are returned in the Error register at the end of the command.

Table 6-2: Diagnostic codes

| Code | Error Type |
|------|----------------------------------|
| 01H | No Error Detected |
| 02H | Formatter Device Error |
| 03H | Sector Buffer Error |
| 04H | ECC Circuitry Error |
| 05H | Controlling Microprocessor Error |
| 8XH | Slave Error |

6.1.3 Erase-Sector(s) – C0H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|---------------------------|-----|---|-------|------------------|---|---|---|
| Command (7) | C0H | | | | | | | |
| C/D/H (6) | X | LBA | X | Drive | Head (LBA 27-24) | | | |
| Cyl High (5) | Cylinder High (LBA 23-16) | | | | | | | |
| Cyl Low (4) | Cylinder Low (LBA 15-8) | | | | | | | |
| Sec Num (3) | Sector Number (LBA 7-0) | | | | | | | |
| Sec Cnt (2) | Sector Count | | | | | | | |
| Feature (1) | X | | | | | | | |

This command is used to pre-erase and condition data sectors in advance of a Write-Without-Erase or Write-Multiple-Without-Erase command. There is no data transfer associated with this command but a Write Fault error status can occur.

6.1.4 Flush-Cache – E7H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|-----|---|-------|---|---|---|---|---|
| Command (7) | E7H | | | | | | | |
| C/D/H (6) | X | | Drive | | X | | | |
| Cyl High (5) | X | | | | | | | |
| Cyl Low (4) | X | | | | | | | |
| Sec Num (3) | X | | | | | | | |
| Sec Cnt (2) | X | | | | | | | |
| Feature (1) | X | | | | | | | |

This command causes the CompactFlash card to complete writing data from its cache. The CompactFlash card then clears BSY and generates an interrupt.

6.1.5 Format-Track – 50H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|---------------------------|-----|---|-------|------------------|---|---|---|
| Command (7) | 50H | | | | | | | |
| C/D/H (6) | X | LBA | X | Drive | Head (LBA 27-24) | | | |
| Cyl High (5) | Cylinder High (LBA 23-16) | | | | | | | |
| Cyl Low (4) | Cylinder Low (LBA 15-8) | | | | | | | |
| Sec Num (3) | Sector Number (LBA 7-0) | | | | | | | |
| Sec Cnt (2) | Sector Count | | | | | | | |
| Feature (1) | X | | | | | | | |

This command is accepted for host backward compatibility. The CompactFlash card expects a sector buffer of data from the host to follow the command with the same protocol as the Write-Sector(s) command although the CompactFlash card does not use the information in the buffer. The use of this command is not recommended.

6.1.6 Identify-Drive – ECH

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|-----|---|---|-------|---|---|---|---|
| Command (7) | E7H | | | | | | | |
| C/D/H (6) | X | | | Drive | X | | | |
| Cyl High (5) | | | | | X | | | |
| Cyl Low (4) | | | | | X | | | |
| Sec Num (3) | | | | | X | | | |
| Sec Cnt (2) | | | | | X | | | |
| Feature (1) | | | | | X | | | |

The Identify-Drive command enables the host to receive parameter information from the CompactFlash card. This command has the same protocol as the Read- Sector(s) command. The parameter words in the buffer have the arrangement and meanings defined in Table 6-3. All reserved bits or words are zero. Table 6-3 is the definition for each field in the Identify-Drive Information.

Table 6-3: Identify-Drive information (1 of 3)

| Word Address | Default Value | Total Bytes | Data Field Type Information |
|--------------|--------------------|-------------|---|
| 0 | 044AH | 2 | General configuration bit-significant information |
| 1 | bbbbH ² | 2 | Default number of cylinders |
| 2 | 0000H | 2 | Reserved |
| 3 | bbbbH ² | 2 | Default number of heads |
| 4 | 0000H | 2 | Reserved |
| 5 | 0200H | 2 | Reserved |
| 6 | bbbbH ² | 2 | Default number of sectors per track |
| 7-8 | bbbbH ² | 4 | Number of sectors per device (Word 7 = MSW, Word 8 = LSW) |
| 9 | xxxxH | 2 | Vendor Unique |
| 10-19 | ddddH ⁴ | 20 | Unique serial number in ASCII |
| 20 | 0002H | 2 | Buffer type |
| 21 | xxxxH | 2 | Buffer size in 512 Byte increments |
| 22 | xxxxH | 2 | # of ECC bytes passed on Read/Write-Long-Sector Commands |

Table 6-3: Identify-Drive information (2 of 3)

| Word Address | Default Value | Total Bytes | Data Field Type Information |
|--------------|--------------------|-------------|---|
| 23-26 | aaaaH ⁵ | 8 | Firmware revision in ASCII. Big Endian Byte Order in Word |
| 27-46 | ccccH ⁶ | 40 | User Definable Model number/name |
| 47 | 8001H | 2 | Maximum number of sectors on Read/Write-Multiple command |
| 48 | 0000H | 2 | Reserved |
| 49 | 0B00H | 2 | Capabilities |
| 50 | 0000H | 2 | Reserved |
| 51 | 0200H | 2 | PIO data transfer cycle timing mode |
| 52 | 0000H | 2 | Reserved |
| 53 | 0007H | 2 | Translation parameters are valid |
| 54 | nnnnH ³ | 2 | Current numbers of cylinders |
| 55 | nnnnH ³ | 2 | Current numbers of heads |
| 56 | nnnnH ³ | 2 | Current sectors per track |
| 57-58 | nnnnH ³ | 4 | Current capacity in sectors (LBAs) (Word 57 = LSW, Word 58 = MSW) |
| 59 | 010xH | 2 | Multiple sector setting |
| 60-61 | nnnnH ³ | 4 | Total number of sectors addressable in LBA Mode |
| 62 | 0000H | 2 | Reserved |
| 63 | 0x07H | 2 | DMA data transfer is supported in ATA Flash Disk Controller |
| 64 | 0003H | 2 | Advanced PIO Transfer Mode Supported |
| 65 | 0078H | 2 | 120ns cycle time support for Multiword DMA Mode-2 |
| 66 | 0078H | 2 | 120ns cycle time support for Multiword DMA Mode-2 |
| 67 | 0078H | 2 | PIO Mode-4 supported |
| 68 | 0078H | 2 | PIO Mode-4 supported |
| 69-79 | 0000H | 20 | Reserved |
| 80 | 007EH | 2 | ATA/ATAPI major version number |
| 81 | 0019H | 2 | ATA/ATAPI minor version number |
| 82 | 706BH | 2 | Features/command sets supported |
| 83 | 400CH | 2 | Features/command sets supported |
| 84 | 4000H | 2 | Features/command sets supported |
| 85-87 | xxxxH | 6 | Features/command sets Enabled |
| 88 | xx1FH | 2 | Ultra DMA Mode supported and selected |
| 89 | xxxxH | 2 | Time required for security erase unit completion |
| 90 | xxxxH | 2 | Time required for enhanced security erase unit completion |

Table 6-3: Identify-Drive information (3 of 3)

| Word Address | Default Value | Total Bytes | Data Field Type Information |
|--------------|---------------|-------------|-----------------------------|
| 91-127 | 0000H | 74 | Reserved |
| 128 | xxxxH | 2 | Security Status |
| 129-159 | 0000H | 62 | Vendor unique bytes |
| 160-162 | xxxxH | 4 | Reserved |
| 163 | xxx2H | 2 | Reserved |
| 164-255 | 0000H | 182 | Reserved |

1. XXXX=This field is subject to change by the host or the device
2. bbbb - default value set by controller. The selections could be user programmable.
3. n - calculated data based on product configuration
4. dddd - unique number of each device
5. aaaa - any unique firmware revision
6. cccc - default value is "xxxMB CompactFlash card" where xxx is the flash drive capacity. The user has an option to change the model number during manufacturing.

1. Word 0: General Configuration

This field informs the host that this is a non-magnetic, hard sectored, removable storage device with a transfer rate greater than 10 MB/sec and is not MFM encoded.

2. Word 1: Default Number of Cylinders

This field contains the number of translated cylinders in the default translation mode. This value will be the same as the number of cylinders.

3. Word 3: Default Number of Heads

This field contains the number of translated heads in the default translation mode.

4. Word 6: Default Number of Sectors per Track

This field contains the number of sectors per track in the default translation mode.

5. Word 7-8: Number of Sectors

This field contains the number of sectors per CompactFlash card. This double word value is also the first invalid address in LBA translation mode. This field is only required by CF feature set support.

6. Word 10-19: Serial Number

Unique serial number ID. The twenty bytes are a user-programmable value with a default value of spaces.

7. Word 20: Buffer Type

This field defines the buffer capability:

0002H: a dual ported multi-sector buffer capable of simultaneous data transfers to or from the host and the CompactFlash card.

8. Word 23-26: Firmware Revision

This field contains the revision of the firmware for this product.

9. Word 27-46: Model Number

This field contains the model number for this product.

10. Word 47: Read-/Write-Multiple Sector Count

This field contains the maximum number of sectors that can be read or written per interrupt using the Read-Multiple or Write-Multiple commands. Only a value of '1' is supported.

11. Word 49: Capabilities

| Bit | Function |
|-----|--|
| 13 | Standby Timer 0: forces sleep mode when host is inactive. |
| 11 | IORDY Support 1: PIO Mode-4 is supported. |
| 9 | LBA Support 1: LBA mode addressing is supported. |
| 8 | DMA Support 1: DMA mode is supported. |

12. Word 51: PIO Data Transfer Cycle Timing Mode

This field defines the mode for PIO data transfer. The CompactFlash card module supports up to PIO Mode-4

13. Word 53: Translation Parameters Valid

| Bit | Function |
|-----|--|
| 0 | 1: Words 54-58 are valid and reflect the current number of cylinders, heads and sectors. |
| 1 | 1: Words 64-70 are valid to support PIO Mode-3 and 4. |
| 2 | 1: Word 88 is valid to support Ultra DMA data transfer. |

14. Word 54-56: Current Number of Cylinders, Heads, Sectors/Track

These fields contain the current number of user addressable Cylinders, Heads, and Sectors/Track in the current translation mode.

15. Word 57-58: Current Capacity

This field contains the product of the current cylinders times heads times sectors.

16. Word 59: Multiple Sector Setting

This field contains a validity flag in the Odd Byte and the current numbers of sectors that can be transferred per interrupt for R/W Multiple in the Even Byte. The Odd Byte is always 01H which indicates that the Even Byte is always valid.

The Even Byte value depends on the value set by the Set Multiple command. The Even Byte of this word by default contains a 00H which indicates that R/W Multiple commands are not valid.

17. Word 60-61: Total Sectors Addressable in LBA Mode

This field contains the number of sectors addressable for the CompactFlash card in LBA mode only.

18. Word 63: Multiword DMA Transfer

This field identifies the Multiword DMA transfer modes supported by the CompactFlash card module and indicates the mode that is currently selected. Only one DMA mode shall be selected at any given time.

| Bit | Function |
|-------|--|
| 15-11 | Reserved |
| 10 | Multiword DMA mode-2 selected 1: Multiword DMA mode-2 is selected and bits 8 and 9 are cleared to 0. 0: Multiword DMA mode-2 is not selected. |
| 9 | Multiword DMA mode-1 selected 1: Multiword DMA mode-1 is selected and 8 and 10 shall be cleared to 0. 0: Multiword DMA mode-1 is not selected. |
| 8 | Multiword DMA mode-0 selected 1: Multiword DMA mode-0 is selected and bits 9 and 10 are cleared to 0. 0: Multiword DMA mode-0 is not selected. |
| 7-3 | Reserved |
| 2 | Multiword DMA mode-2 supported 1: Multiword DMA mode-2 and below are supported and Bits 0 and 1 shall be set to 1. |
| 1 | Multiword DMA mode-1 supported 1: Multiword DMA mode-1 and below are supported. |
| 0 | Multiword DMA mode-0 supported 1: Multiword DMA mode-0 is supported. |

19. Word 64: Advanced PIO Data Transfer Mode

Bit (7:0) is defined as the PIO data and register transfer supported field. If this field is supported, Bit 1 of word 53 shall be set to one. This field is bit significant. Any number of bits may be set to one in this field by the device to indicate the PIO modes the device is capable of supporting. Of these bits, bit (7:2) are Reserved for future PIO modes.

| Bit | Function |
|-----|-----------------------------|
| 0 | 1: PIO Mode-3 is supported. |
| 1 | 1: PIO Mode-4 is supported. |

20. Word 65: Minimum Multiword DMA Transfer Cycle Time Per Word

This field defines the minimum Multiword DMA transfer cycle time per word. This field defines, in nanoseconds, the minimum cycle time that the CompactFlash card supports when performing Multiword DMA transfers on a per word basis. The CompactFlash card supports up to Multiword DMA Mode-2, so this field is set to 120ns.

21. Word 66: Device Recommended Multiword DMA Cycle Time

This field defines the CompactFlash card recommended Multiword DMA transfer cycle time. This field defines, in nanoseconds, the minimum cycle time per word during a single sector host transfer while performing a multiple sector READ DMA or WRITE DMA command for any location on the media under nominal conditions. If a host runs at a faster cycle rate by operating at a cycle time of less than this value, the CompactFlash card may negate DMARQ for flow control. The rate at which DMARQ is negated could result in reduced throughput despite the faster cycle rate. Transfer at this rate does not ensure that flow control will not be used, but implies that higher performance may result. The CompactFlash card supports up to Multiword DMA Mode-2, so this field is set to 120ns.

22. Word 67: Minimum PIO Transfer Cycle Time Without Flow Control

This field defines, in nanoseconds, the minimum cycle time that, if used by the host, the device guarantees data integrity during the transfer without utilization of IORDY flow control. If this field is supported, Bit 1 of word 53 shall be set to one. The CompactFlash card minimum cycle time is 120 ns. A value of 0078H is reported.

23. Word 68: Minimum PIO Transfer Cycle Time with IORDY

This field defines, in nanoseconds, the minimum cycle time that the device supports while performing data transfer while utilizing IORDY flow control. If this field is supported, Bit 1 of word 53 shall be set to one. The CompactFlash card minimum cycle time is 120 ns, e.g., PIO mode 4. A value of 0078H is reported.

24. Word 80: Major Version Number

If not 0000H or FFFFH, the device claims compliance with the major version(s) as indicated by bits (6:1) being set to one. Since ATA standards maintain downward compatibility, a device may set more than one bit. The CompactFlash card supports ATA-1 to ATA-6.

25. Word 81: Minor Version Number

If an implementer claims that the revision of the standard they used to guide their implementation does not need to be reported or if the implementation was based upon a standard prior to the ATA-3 standard, word 81 shall be 0000H or FFFFH. A value of 0019H reported in word 81 indicates ATA/ATAPI-6 T13 1410D revision 3a guided the implementation.

26. Words 82-84: Features/command sets supported

Words 82, 83, and 84 indicate the features and command sets supported.

Word 82

| Bit | Function |
|-----|---|
| 15 | 0: Obsolete |
| 14 | 1: NOP command is supported |
| 13 | 1: Read Buffer command is supported |
| 12 | 1: Write Buffer command is supported |
| 11 | 0: Obsolete |
| 10 | 0: Host Protected Area feature set is not supported |
| 9 | 0: Device Reset command is not supported |
| 8 | 0: Service interrupt is not supported |
| 7 | 0: Release interrupt is not supported |
| 6 | 1: Look-ahead is supported |
| 5 | 1: Write cache is supported |
| 4 | 0: Packet Command feature set is not supported |
| 3 | 1: Power Management feature set is supported |
| 2 | 0: Removable Media feature set is not supported |
| 1 | 1: Security Mode feature set is supported |
| 0 | 0: SMART feature set is not supported |

Word 83

The values in this word should not be depended on by host implementers.

| Bit | Function |
|------|--|
| 15 | 0: Provides indications that the features/command sets supported words are not valid |
| 14 | 1: Provides indications that the features/command sets supported words are valid |
| 13-9 | 0: Reserved |
| 8 | 1: Set-Max security extension supported |
| 7-5 | 0: Reserved |
| 4 | 0: Removable Media Status feature set is not supported |
| 3 | 1: Advanced Power Management feature set is not supported |
| 2 | 1: CFA feature set is not supported |
| 1 | 0: Read DMA Queued and Write DMA Queued commands are not supported |
| 0 | 1: Download Microcode command is not supported |

Word 84

The values in this word should not be depended on by host implementers.

| Bit | Function |
|-----|----------|
|-----|----------|

| | |
|------|--|
| 15 | 0: Provides indications that the features/command sets supported words are valid |
| 14 | 1: Provides indications that the features/command sets supported words are valid |
| 13-0 | 0: Reserved |

27. Words 85-87: Features/command sets enabled

Words 85, 86, and 87 indicate features/command sets enabled. The host can enable/disable the features or command set only if they are supported in Words 82-84.

Word 85

| Bit | Function |
|-----|----------|
|-----|----------|

| | |
|----|--|
| 15 | 0: Obsolete |
| 14 | 0: NOP command is not enabled 1: NOP command is enabled |
| 13 | 0: Read Buffer command is not enabled 1: Read Buffer command is enabled |
| 12 | 0: Write Buffer command is not enabled 1: Write Buffer command is enabled |
| 11 | 0: Obsolete |
| 10 | 1: Host Protected Area feature set is not enabled |
| 9 | 0: Device Reset command is not enabled |
| 8 | 0: Service interrupt is not enabled |
| 7 | 0: Release interrupt is not enabled |
| 6 | 0: Look-ahead is not enabled 1: Look-ahead is enabled |
| 5 | 0: Write cache is not enabled 1: Write cache is enabled |
| 4 | 0: Packet Command feature set is not enabled |
| 3 | 0: Power Management feature set is not enabled 1: Power Management feature set is enabled |
| 2 | 0: Removable Media feature set is not enabled |
| 1 | 0: Security Mode feature set has not been enabled via the Security Set Password command 1: Security Mode feature set has been enabled via the Security Set Password command |
| 0 | 0: SMART feature set is not enabled |

Word 86

| Bit | Function |
|-----|----------|
|-----|----------|

| | |
|------|--|
| 15-9 | 0: Reserved |
| 8 | 1: Set-Max security extension enabled |
| 7-5 | 0: Reserved |
| 4 | 0: Removable Media Status feature set is not enabled |
| 3 | 0: Advanced Power Management feature set is not enabled via the Set Features command 1: Advanced Power Management feature set is enabled via the Set Features command |
| 2 | 0: CFA feature set is disabled |
| 1 | 0: Read DMA Queued and Write DMA Queued commands are not enabled |
| 0 | 0: Download Microcode command is not enabled |

Word 87

The values in this word should not be depended on by host implementers.

| Bit | Function |
|-----|----------|
|-----|----------|

| | |
|------|--|
| 15 | 0: Provides indications that the features/command sets supported words are valid |
| 14 | 1: Provides indications that the features/command sets supported words are valid |
| 13-0 | 0: Reserved |

Word 88

| Bit | Function |
|-------|--|
| 15-13 | Reserved |
| 12 | 1: Ultra DMA mode-4 is selected 0: Ultra DMA mode-4 is not selected |
| 11 | 1: Ultra DMA mode-3 is selected 0: Ultra DMA mode-3 is not selected |
| 10 | 1: Ultra DMA mode-2 is selected 0: Ultra DMA mode-2 is not selected |
| 9 | 1: Ultra DMA mode-1 is selected 0: Ultra DMA mode-1 is not selected |
| 8 | 1: Ultra DMA mode-0 is selected 0: Ultra DMA mode-0 is not selected |
| 7-5 | Reserved |
| 4 | 1: Ultra DMA mode-4 and below are supported |
| 3 | 1: Ultra DMA mode-3 and below are supported |
| 2 | 1: Ultra DMA mode-2 and below are supported |
| 1 | 1: Ultra DMA mode-1 and below are supported |
| 0 | 1: Ultra DMA mode-0 is supported |

28. Word 89: Time required for Security erase unit completion

Word 89 specifies the time required for the Security Erase Unit command to complete.

| Value | Time |
|-------|---------------------|
| 0 | Value Not Specified |
| 1-254 | (Value * 2) minutes |
| 255 | >508 minutes |

29. Word 90: Time required for Enhanced security erase unit completion

Word 90 specifies the time required for the Enhanced Security Erase Unit command to complete.

| Value | Time |
|-------|---------------------|
| 0 | Value Not Specified |
| 1-254 | (Value * 2) minutes |
| 255 | >508 minutes |

30. Word 128: Security Status

| Bit | Function |
|------------|---|
| 8 | Security Level 1: Security mode is enabled and the security level is the maximum 0: and security mode is enabled, indicates that the security level is high |
| 5 | Enhanced security erase unit feature supported 1: Enhanced security erase unit feature set is supported |
| 4 | Expire 1: Security count has expired and Security Unlock and Security Erase Unit are command aborted until a power-on reset or hard reset |
| 3 | Freeze 1: Security is frozen |
| 2 | Lock 1: Security is locked |
| 1 | Enable/Disable 1: Security is enabled 0: Security is disabled |
| 0 | Capability 1: Supports security mode feature set 0: Does not support security mode feature set |

6.1.7 Idle – E3H or 97H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|--------------------------------|---|---|-------|---|---|---|---|
| Command (7) | E3H or 97H | | | | | | | |
| C/D/H (6) | X | | | Drive | X | | | |
| Cyl High (5) | | | | | X | | | |
| Cyl Low (4) | | | | | X | | | |
| Sec Num (3) | | | | | X | | | |
| Sec Cnt (2) | Timer Count (5msec increments) | | | | | | | |
| Feature (1) | | | | | X | | | |

This command causes the CompactFlash card to set BSY, enter the Idle Mode, clear BSY and generate an interrupt. If the sector count is non-zero, it is interpreted as a timer count with each count being 5 milliseconds and the automatic power down mode is enabled. If the sector count is zero and the automatic power down mode is also enabled, the timer count is set to 3, with each count being 5ms. Note that this time base (5msec) is different from the ATA specification.

6.1.8 Idle-Immediate – E1H or 95H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|------------|---|---|-------|---|---|---|---|
| Command (7) | E1H or 95H | | | | | | | |
| C/D/H (6) | X | | | Drive | X | | | |
| Cyl High (5) | | | | | X | | | |
| Cyl Low (4) | | | | | X | | | |
| Sec Num (3) | | | | | X | | | |
| Sec Cnt (2) | | | | | X | | | |
| Feature (1) | | | | | X | | | |

This command causes the CompactFlash card to set BSY, enter the Idle Mode, clear BSY and generate an interrupt.

6.1.9 Initialize-Drive-Parameters - 91H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|-------------------|---|---|-------|---------------------------|---|---|---|
| Command (7) | 91H | | | | | | | |
| C/D/H (6) | X | 0 | X | Drive | Max Head (no. of heads-1) | | | |
| Cyl High (5) | | | | | X | | | |
| Cyl Low (4) | | | | | X | | | |
| Sec Num (3) | | | | | X | | | |
| Sec Cnt (2) | Number of Sectors | | | | | | | |
| Feature (1) | X | | | | | | | |

This command enables the host to set the number of sectors per track and the number of heads per cylinder. Only the Sector Count and the Drive/Head registers are used by this command.

6.1.10 NOP - 00H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|-----|---|---|-------|---|---|---|---|
| Command (7) | 00H | | | | | | | |
| C/D/H (6) | X | | | Drive | X | | | |
| Cyl High (5) | | | | | X | | | |
| Cyl Low (4) | | | | | X | | | |
| Sec Num (3) | | | | | X | | | |
| Sec Cnt (2) | | | | | X | | | |
| Feature (1) | X | | | | | | | |

This command always fails with the CompactFlash card returning command aborted.

6.1.11 Read-Buffer - E4H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|-----|---|---|-------|---|---|---|---|
| Command (7) | E4H | | | | | | | |
| C/D/H (6) | X | | | Drive | X | | | |
| Cyl High (5) | | | | | X | | | |
| Cyl Low (4) | | | | | X | | | |
| Sec Num (3) | | | | | X | | | |
| Sec Cnt (2) | | | | | X | | | |
| Feature (1) | X | | | | | | | |

The Read Buffer command enables the host to read the current contents of the CompactFlash card's sector buffer. This command has the same protocol as the Read Sector(s) command.

6.1.12 Read DMA – C8H or C9H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|---------------------------|-----|---|-------|------------------|---|---|---|
| Command (7) | C8H or C9H | | | | | | | |
| C/D/H (6) | 1 | LBA | 1 | Drive | Head (LBA 27-24) | | | |
| Cyl High (5) | Cylinder High (LBA 23-16) | | | | | | | |
| Cyl Low (4) | Cylinder Low (LBA 15-8) | | | | | | | |
| Sec Num (3) | Sector Number (LBA 7-0) | | | | | | | |
| Sec Cnt (2) | Sector Count | | | | | | | |
| Feature (1) | X | | | | | | | |

This command executes in a similar manner to the READ SECTOR (S) command except for the following:

- The host initializes the DMA channel prior to issuing the command;
- Data transfers are qualified by DMARQ and are performed by the DMA channel;
- The CompactFlash card issues only one interrupt per command to indicate that data transfer has terminated and status is available.

During the DMA transfer phase of a READ DMA command, the CompactFlash card shall provide status of the BSY bit or the DRQ bit until the command is completed. At command completion, the command block registers contain the cylinder, head and sector number (LBA) of the last sector read.

If an error occurs, the read terminates at the sector where the error occurred. The flawed data is pending in the sector buffer. Subsequent sectors are transferred only if the error was a correctable data error. All other errors cause Read-DMA to stop after transfer of the sector that contained the error.

For Ultra-DMA mode, if a CRC error is detected during transfer, the ICRC and ABRT bits of the Error register are set at the end of the command.

6.1.13 Read-Multiple – C4H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|---------------------------|-----|---|-------|------------------|---|---|---|
| Command (7) | C4H | | | | | | | |
| C/D/H (6) | X | LBA | X | Drive | Head (LBA 27-24) | | | |
| Cyl High (5) | Cylinder High (LBA 23-16) | | | | | | | |
| Cyl Low (4) | Cylinder Low (LBA 15-8) | | | | | | | |
| Sec Num (3) | Sector Number (LBA 7-0) | | | | | | | |
| Sec Cnt (2) | Sector Count | | | | | | | |
| Feature (1) | X | | | | | | | |

The Read- Multiple command is similar to the Read- Sector(s) command. Interrupts are not generated on every sector, but on the transfer of a block which contains the number of sectors defined by a Set-Multiple command.

Command execution is identical to the Read- Sectors operation except that the numbers of sectors defined by a Set-Multiple command are transferred without intervening interrupts. DRQ qualification of the transfer is required only at the start of the data block, not on each sector.

The block count of sectors to be transferred without intervening interrupts is programmed by the Set-Multiple Mode command, which must be executed prior to the Read- Multiple command. When the Read-Multiple command is issued, the Sector Count register contains the number of sectors (not the number of blocks or the block count) requested. If the number of requested sectors is not evenly divisible by the block count, as many full blocks as possible are transferred, followed by a final, partial block transfer.

The partial block transfer is for n sectors, where $n = \text{remainder}(\text{sector count}/\text{block count})$. If the Read-Multiple command is attempted before the Set-Multiple Mode command has been executed or when Read-Multiple commands are disabled, the Read-Multiple operation is rejected with an Aborted Command error. Disk errors encountered during Read- Multiple commands are posted at the beginning of the block or partial block transfer, but DRQ is still set and the data transfer will take place as it normally would, including transfer of corrupted data, if any.

Interrupts are generated when DRQ is set at the beginning of each block or partial block. The error reporting is the same as that on a Read-Sector(s) Command. This command reads from 1 to 256 sectors as specified in the Sector Count register. A sector counts of 0 requests 256 sectors. The transfer begins at the sector specified in the Sector Number register.

At command completion, the Command Block registers contain the cylinder, head and sector number of the last sector read. If an error occurs, the read terminates at the sector where the error occurred. The Command Block registers contain the cylinder, head and sector number of the sector where the error occurred. The flawed data is pending in the sector buffer.

Subsequent blocks or partial blocks are transferred only if the error was a correctable data error. All other errors cause the command to stop after transfer of the block which contained the error.

6.1.14 Read Sectors – 20H or 21H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|---------------------------|-----|---|-------|------------------|---|---|---|
| Command (7) | 20H or 21H | | | | | | | |
| C/D/H (6) | X | LBA | X | Drive | Head (LBA 27-24) | | | |
| Cyl High (5) | Cylinder High (LBA 23-16) | | | | | | | |
| Cyl Low (4) | Cylinder Low (LBA 15-8) | | | | | | | |
| Sec Num (3) | Sector Number (LBA 7-0) | | | | | | | |
| Sec Cnt (2) | Sector Count | | | | | | | |
| Feature (1) | X | | | | | | | |

This command reads from 1 to 256 sectors as specified in the Sector Count register. A sectors count of 0 requests 256 sectors. The transfer begins at the sector specified in the Sector Number register. When this command is issued and after each sector of data (except the last one) has been read by the host, the CompactFlash card sets BSY, puts the sector of data in the buffer, sets DRQ, clears BSY, and generates an interrupt. The host then reads the 512 bytes of data from the buffer.

At command completion, the Command Block registers contain the cylinder, head and sector number of the last sector read. If an error occurs, the read terminates at the sector where the error occurred. The Command Block registers contain the cylinder, head, and sector number of the sector where the error occurred. The flawed data is pending in the sector buffer.

6.1.15 Read Verify Sector(s) – 40H or 41H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|---------------------------|-----|---|-------|------------------|---|---|---|
| Command (7) | 40H or 41H | | | | | | | |
| C/D/H (6) | X | LBA | X | Drive | Head (LBA 27-24) | | | |
| Cyl High (5) | Cylinder High (LBA 23-16) | | | | | | | |
| Cyl Low (4) | Cylinder Low (LBA 15-8) | | | | | | | |
| Sec Num (3) | Sector Number (LBA 7-0) | | | | | | | |
| Sec Cnt (2) | Sector Count | | | | | | | |
| Feature (1) | X | | | | | | | |

This command is identical to the Read- Sectors command, except that DRQ is never set and no data is transferred to the host. When the command is accepted, the CompactFlash card sets BSY.

When the requested sectors have been verified, the CompactFlash card clears BSY and generates an interrupt. Upon command completion, the Command Block registers contain the cylinder, head, and sector number of the last sector verified.

If an error occurs, the Verify terminates at the sector where the error occurs. The Command Block registers contain the cylinder, head and sector number of the sector where the error occurred. The Sector Count register contains the number of sectors not yet verified.

6.1.16 Recalibrate – 1XH

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|-----|-----|---|-------|---|---|---|---|
| Command (7) | 1XH | | | | | | | |
| C/D/H (6) | X | LBA | X | Drive | | | X | |
| Cyl High (5) | | | | | X | | | |
| Cyl Low (4) | | | | | X | | | |
| Sec Num (3) | | | | | X | | | |
| Sec Cnt (2) | | | | | X | | | |
| Feature (1) | | | | | X | | | |

This command is effectively a no operation command to the CompactFlash card and is provided for compatibility purposes.

6.1.17 Request-sense – 03H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|-----|---|---|-------|---|---|---|---|
| Command (7) | 03H | | | | | | | |
| C/D/H (6) | | X | | Drive | | | X | |
| Cyl High (5) | | | | | X | | | |
| Cyl Low (4) | | | | | X | | | |
| Sec Num (3) | | | | | X | | | |
| Sec Cnt (2) | | | | | X | | | |
| Feature (1) | | | | | X | | | |

This command requests extended error information for the previous command. Table 6-4 defines the valid extended error codes for the CompactFlash card. The extended error code is returned to the host in the Error register.

Table 6-4: Extended Error Codes

| Extended Error Code | Description |
|-------------------------|--|
| 00H | No Error Detected |
| 01H | Self Test OK (No Error) |
| 09H | Miscellaneous Error |
| 20H | Invalid Command |
| 21H | Invalid Address (Requested Head or Sector Invalid) |
| 2FH | Address Overflow (Address Too Large) |
| 35H, 36H | Supply or generated Voltage Out of Tolerance |
| 11H | Uncorrectable ECC Error |
| 18H | Corrected ECC Error |
| 05H, 30-34H, 37H, 3EH | Self Test or Diagnostic Failed |
| 10H, 14H | ID Not Found |
| 3AH | Spare Sectors Exhausted |
| 1FH | Data Transfer Error / Aborted Command |
| 0CH, 38H, 3BH, 3CH, 3FH | Corrupted Media Format |
| 03H | Write / Erase Failed |
| 22H | Power Level 1 Disabled |

6.1.18 Seek – 7XH

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|---------------------------|-----|---|-------|------------------|---|---|---|
| Command (7) | 7XH | | | | | | | |
| C/D/H (6) | X | LBA | X | Drive | Head (LBA 27-24) | | | |
| Cyl High (5) | Cylinder High (LBA 23-16) | | | | | | | |
| Cyl Low (4) | Cylinder Low (LBA 15-8) | | | | | | | |
| Sec Num (3) | Sector Number (LBA 7-0) | | | | | | | |
| Sec Cnt (2) | Sector Count | | | | | | | |
| Feature (1) | X | | | | | | | |

This command is effectively a NOP command to the CompactFlash card although it does perform a range check of cylinder and head or LBA address and returns an error if the address is out of range.

6.1.19 Set-Features – EFH

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|---------|---|-------|---|---|---|---|---|
| Command (7) | EFH | | | | | | | |
| C/D/H (6) | X | | Drive | | X | | | |
| Cyl High (5) | X | | | | | | | |
| Cyl Low (4) | X | | | | | | | |
| Sec Num (3) | X | | | | | | | |
| Sec Cnt (2) | Config | | | | | | | |
| Feature (1) | Feature | | | | | | | |

This command is used by the host to establish or select certain features. Table 6-5 defines all features that are supported.

| Feature | Operation |
|---------|---|
| 01H | Enable 8-bit data transfers. |
| 03H | Set transfer mode based on value in Sector Count register. Table 11-6 defines the values. |
| 55H | Disable Read Look Ahead. |
| 66H | Disable Power on Reset (POR) establishment of defaults at software Reset. |
| 69H | NOP - Accepted for backward compatibility. |
| 81H | Disable 8-bit data transfer. |
| 96H | NOP - Accepted for backward compatibility. |
| 97H | Accepted for backward compatibility. Use of this Feature is not recommended. |
| 9AH | NOP - accepted for compatibility. |
| BBH | 4 Bytes of data apply on Read/Write-Long-Sector commands. |
| AAH | Enable Read Look Ahead. |
| CCH | Enable Power on Reset (POR) establishment of defaults at software Reset. |

Features 01H and 81H are used to enable and clear 8-bit data transfer mode. If the 01H feature command is issued all data transfers will occur on the low order D₇-D₀ data bus and the IOCS16# signal will not be asserted for data register accesses.

Features 02H and 82H allow the host to enable or disable write cache in the CompactFlash card that implements write cache. When the subcommand Disable-Write-Cache is issued, the CompactFlash card should initiate the sequence to flush cache to non-volatile memory before command completion.

Feature 03H allows the host to select the transfer mode by specifying a value in the Sector Count register. The upper 5 bits define the type of transfer and the low order 3 bits encode the mode value. One PIO mode is selected at all times. The host may change the selected modes by the Set-Features command.

Feature 55H is the default feature for the CompactFlash card. Therefore, the host does not have to issue Set-Features command with this feature unless it is necessary for compatibility reasons.

Features 66H and CCH can be used to enable and disable whether the Power-on Reset (POR) Defaults will be set when a software reset occurs.

Table 6-6: Transfer mode values

| Mode | Bits [7:3] | Bits [2:0] |
|---------------------------------|------------|-------------------|
| PIO default mode | 00000b | 000b |
| PIO default mode, disable IORDY | 00000b | 001b |
| PIO flow control transfer mode | 00001b | mode ¹ |
| Multiword DMA mode | 00100b | mode ¹ |
| Ultra DMA mode | 01000b | mode ¹ |
| Reserved | Other | N/A |

1. Mode = transfer mode number, all other values are not valid

6.1.20 SMART – B0H

Smart Command signature is defined as cylinder being C2H to F4H. The feature register will indicate the subcommand as listed below.

6.1.20.1 SMART Return Status – DAH

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------------|-----|---|---|-------|---|---|---|---|
| Command (7) | B0H | | | | | | | |
| C/D/H (6) | | X | | Drive | | | X | |
| Cyl High (5) | C2H | | | | | | | |
| Cyl Low (4) | 4FH | | | | | | | |
| Sec Num (3) | X | | | | | | | |
| Sec Cnt (2) | X | | | | | | | |
| Feature (1) | DAH | | | | | | | |

This Command is used to communicate the reliability status of the device to the host at the host's request. If the device has not detected a threshold exceeded condition, the device sets the LBA Mid register to 4FH and the LBA High register to C2H. If the device has detected a threshold exceeded condition, the device sets the LBA Mid register to F4H and the LBA High register to 2CH. In the current implementation, the only threshold checked is that if a fatal error has occurred.

6.1.20.2 SMART Enable/Disable Attribute Autosave – D2H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|------------|---|-------|---|---|---|---|---|
| Command (7) | B0H | | | | | | | |
| C/D/H (6) | X | | Drive | | X | | | |
| Cyl High (5) | C2H | | | | | | | |
| Cyl Low (4) | 4FH | | | | | | | |
| Sec Num (3) | X | | | | | | | |
| Sec Cnt (2) | 00H or F1H | | | | | | | |
| Feature (1) | D2H | | | | | | | |

This Command enables or disables the optional attribute autosave feature of the device. A value of 00H in the Sec Cnt register will disable the autosave feature. A value of F1H in the Sec Cnt register will enable the autosave feature. Currently, no action is generated by this command since there is no online collection of data.

6.1.20.3 SMART Enable Operations – D8H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|-----|---|-------|---|---|---|---|---|
| Command (7) | B0H | | | | | | | |
| C/D/H (6) | X | | Drive | | X | | | |
| Cyl High (5) | C2H | | | | | | | |
| Cyl Low (4) | 4FH | | | | | | | |
| Sec Num (3) | X | | | | | | | |
| Sec Cnt (2) | X | | | | | | | |
| Feature (1) | D8H | | | | | | | |

This Command enables access to all SMART capabilities within the device. Prior to receipt of this command, SMART data is collected but not accessible via SMART. The state of SMART (either enabled or disabled) shall be preserved by the device across power cycles. Once enabled, the receipt of subsequent SMART ENABLE OPERATIONS commands shall not affect any SMART data or functions.

6.1.20.4 SMART Disable Operations – D9H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|-----|---|-------|---|---|---|---|---|
| Command (7) | B0H | | | | | | | |
| C/D/H (6) | X | | Drive | | X | | | |
| Cyl High (5) | C2H | | | | | | | |
| Cyl Low (4) | 4FH | | | | | | | |
| Sec Num (3) | X | | | | | | | |
| Sec Cnt (2) | X | | | | | | | |
| Feature (1) | D9H | | | | | | | |

This Command disables access to SMART data via SMART commands. After receipt of this command the device shall disable all SMART operations. However SMART data shall continue to be collected and accessible when SMART is next enabled. The state of SMART (either enabled or disabled) shall be preserved by the device across power cycles. After receipt of this command by the device, all other SMART commands, including SMART DISABLE OPERATIONS commands, with the exception of SMART ENABLE OPERATIONS, are disabled and invalid, and the commands shall be aborted by the device.

6.1.20.5 SMART Execute Offline – D4H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|---------------------|---|-------|---|---|---|---|---|
| Command (7) | B0H | | | | | | | |
| C/D/H (6) | X | | Drive | | X | | | |
| Cyl High (5) | C2H | | | | | | | |
| Cyl Low (4) | 4FH | | | | | | | |
| Sec Num (3) | Subcommand Specific | | | | | | | |
| Sec Cnt (2) | X | | | | | | | |
| Feature (1) | D4H | | | | | | | |

This Command causes the device to immediately initiate the optional set of activities that collect SMART data in an off-line mode and the save this data to the device’s memory. This data is not retained across resets and a new command must be executed to recollect data. The SMART data collected is determined by the subcommand specified in the Sec Num register. All subcommands other than listed below will be aborted. Valid subcommands will be executed in captive mode and the device will set BSY bit until command is completed. The collected data should be read by a subsequent SMART Read Data (D0H) command.

SMART EXECUTE OFF-LINE Sector Number register values (sub-command specific)

| Subcommand | Collected Data |
|-------------------|---|
| 0-201 | Reserved |
| 202 (0xCA) | Bad block count (captive) |
| 203 (0xCB) | Group free block count (captive) |
| 204 (0xCC) | Group average age (captive) |
| 205 (0xCD) | Group maximum age (captive) |
| 206 (0xCE) | Group minimum age (captive) |
| 207 (0xCF) | Group wear swap count (captive) |
| 208 (0xD0) | Group retention swap count (captive) |
| 209 (0xD1) | Group total block erase count (captive) |
| 210-255 | Reserved |

6.1.20.6 SMART Read Data – D0H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------------|-----|---|-------|---|---|---|---|---|
| Command (7) | B0H | | | | | | | |
| C/D/H (6) | X | | Drive | | X | | | |
| Cyl High (5) | C2H | | | | | | | |
| Cyl Low (4) | 4FH | | | | | | | |
| Sec Num (3) | X | | | | | | | |
| Sec Cnt (2) | X | | | | | | | |
| Feature (1) | D0H | | | | | | | |

This Command returns the Device SMART data structure to the host. This command must be preceded by the SMART Execute Offline command with an appropriate subcommand listed above. The returned data will depend on the requested subcommand.

All returned data comply with the SMART data structure as specified in the ATA spec. Bytes 0 to 361 of the structure returns SST specific data that depends of the requested subcommand. Bytes 362 to 385 are standard values as defined in the ATA spec. bytes 386 to 510 returns SST specific data common to all subcommands. Byte 511 is the 2's complement checksum of all bytes in the data structure.

Offline Data Collection Status (byte 362)

The offline data collection status byte indicates whether SMART data collection was successful or not. The host should check this value in the returned data structure before proceeding with interpretation of vendor specific data bytes. The follow are possible status values.

| Value | Definition |
|-------|---|
| 00H | Offline data collection activity was never started. |
| 02H | Offline data collection activity was completed without error. |
| 04H | Offline data collection activity was suspended host. |
| 05H | Offline data collection activity was aborted by host. |
| 06H | Offline data collection activity was aborted by device. |

6.1.21 Set-Multiple-Mode – C6H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------------|--------------|---|-------|---|---|---|---|---|
| Command (7) | C6H | | | | | | | |
| C/D/H (6) | X | | Drive | | X | | | |
| Cyl High (5) | X | | | | | | | |
| Cyl Low (4) | X | | | | | | | |
| Sec Num (3) | X | | | | | | | |
| Sec Cnt (2) | Sector Count | | | | | | | |
| Feature (1) | X | | | | | | | |

This command enables the CompactFlash card to perform Read and Write Multiple operations and establishes the block count for these commands. The Sector Count register is loaded with the number of sectors per block. Upon receipt of the command, the CompactFlash card sets BSY to 1 and checks the Sector Count register.

If the Sector Count register contains a valid value and the block count is supported, the value is loaded for all subsequent Read-Multiple and Write-Multiple commands and execution of those commands is enabled. If a block count is not supported, an Aborted command error is posted, and Read- Multiple and Write- Multiple commands are disabled. If the Sector Count registers contains 0 when the command is issued, Read and Write- Multiple commands are disabled. At power-on, or after a hardware or (unless disabled by a Set-Feature command) software reset, the default mode is Read and Write-Multiple disabled.

6.1.22 Set-Sleep-Mode – E6H or 99H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|------------|---|-------|---|---|---|---|---|
| Command (7) | E6H or 99H | | | | | | | |
| C/D/H (6) | X | | Drive | | X | | | |
| Cyl High (5) | | | | | X | | | |
| Cyl Low (4) | | | | | X | | | |
| Sec Num (3) | | | | | X | | | |
| Sec Cnt (2) | | | | | X | | | |
| Feature (1) | | | | | X | | | |

This command causes the CompactFlash card to set BSY, enter the Sleep mode, clear BSY and generate an interrupt. Recovery from sleep mode is accomplished by simply issuing another command (a reset is permitted but not required). Sleep mode is also entered when internal timers expire so the host does not need to issue this command except when it wishes to enter Sleep mode immediately. The default value for the timer is 15 milliseconds.

6.1.23 Standby – E2H or 96H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|------------|---|-------|---|---|---|---|---|
| Command (7) | E2H or 96H | | | | | | | |
| C/D/H (6) | X | | Drive | | X | | | |
| Cyl High (5) | | | | | X | | | |
| Cyl Low (4) | | | | | X | | | |
| Sec Num (3) | | | | | X | | | |
| Sec Cnt (2) | | | | | X | | | |
| Feature (1) | | | | | X | | | |

This command causes the CompactFlash card to set BSY, enter the Sleep mode (which corresponds to the ATA “Standby” Mode), clear BSY and return the interrupt immediately. Recovery from Sleep mode is accomplished by simply issuing another command (a reset is not required).

6.1.24 Standby-Immediate – E0H or 94H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|------------|---|---|-------|---|---|---|---|
| Command (7) | E0H or 94H | | | | | | | |
| C/D/H (6) | | X | | Drive | | | X | |
| Cyl High (5) | | | | | X | | | |
| Cyl Low (4) | | | | | X | | | |
| Sec Num (3) | | | | | X | | | |
| Sec Cnt (2) | | | | | X | | | |
| Feature (1) | | | | | X | | | |

This command causes the CompactFlash card to set BSY, enter the Sleep mode (which corresponds to the ATA “Standby” Mode), clear BSY and return the interrupt immediately. Recovery from Sleep mode is accomplished by simply issuing another command (a reset is not required).

6.1.25 Translate-Sector – 87H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|---------------------------|-----|---|-------|---|------------------|---|---|
| Command (7) | 87H | | | | | | | |
| C/D/H (6) | 1 | LBA | 1 | Drive | | Head (LBA 27-24) | | |
| Cyl High (5) | Cylinder High (LBA 23-16) | | | | | | | |
| Cyl Low (4) | Cylinder Low (LBA 15-8) | | | | | | | |
| Sec Num (3) | Sector Number (LBA 7-0) | | | | | | | |
| Sec Cnt (2) | | | | | X | | | |
| Feature (1) | | | | | X | | | |

This command allows the host a method of determining the exact number of times a user sector has been erased and programmed. The controller responds with a 512 Byte buffer of information containing the desired cylinder, head, and sector, including its logical address, and the Hot Count, if available, for that sector. Table 6-7 represents the information in the buffer. Please note that this command is unique to the CompactFlash card.

Table 6-7: Translate-Sector Information

| Address | Information |
|----------|--|
| 00H-01H | Cylinder MSB (00), Cylinder LSB (01) |
| 02H | Head |
| 03H | Sector |
| 04H-06H | LBA MSB (04) - LSB (06) |
| 07H-12H | Reserved |
| 13H | Erased flag (FFh) = Erased; 00h = Not erased |
| 14H-17H | Reserved |
| 18H-1AH | Hot Count MSB (18) - LSB (1A) ¹ |
| 1BH-1FFH | Reserved |

1. A value of 0 indicates Hot Count is not supported.



6.1.26 Write-Buffer - E8H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|-----|---|---|-------|---|---|---|---|
| Command (7) | E8H | | | | | | | |
| C/D/H (6) | | X | | Drive | | | X | |
| Cyl High (5) | | | | | X | | | |
| Cyl Low (4) | | | | | X | | | |
| Sec Num (3) | | | | | X | | | |
| Sec Cnt (2) | | | | | X | | | |
| Feature (1) | | | | | X | | | |

The Write-Buffer command enables the host to overwrite contents of the CompactFlash card sector buffer with any data pattern desired. This command has the same protocol as the Write-Sector(s) command and transfers 512 bytes.

6.1.27 Write-DMA - CAH or CBH

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|---------------------------|-----|---|-------|------------------|---|---|---|
| Command (7) | CAH or CBH | | | | | | | |
| C/D/H (6) | 1 | LBA | 1 | Drive | Head (LBA 27-24) | | | |
| Cyl High (5) | Cylinder High (LBA 23-16) | | | | | | | |
| Cyl Low (4) | Cylinder Low (LBA 15-8) | | | | | | | |
| Sec Num (3) | Sector Number (LBA 7-0) | | | | | | | |
| Sec Cnt (2) | Sector Count | | | | | | | |
| Feature (1) | X | | | | | | | |

This command executes in a similar manner to Write-RITE Sector(s) except for the following:

- The host initializes the DMA channel prior to issuing the command
- Data transfers are qualified by DMARQ and are performed by the DMA channel
- The CompactFlash card issues only one interrupt per command to indicate that data transfer has terminated and status is available.

During the execution of a Write-RITE DMA command, the CompactFlash card shall provide status of the BSY bit or the DRQ bit until the command is completed. At command completion, the command block registers contain the cylinder, head and sector number (LBA) of the last sector read.

If an error occurs after the attempted write of a transferred sector, the command is terminated and subsequent blocks are not transferred. The command block registers contain the cylinder, head and sector number of the sector where the error occurred and the Sector Count register contains the residual number of sectors for successful completion of the command.

For Ultra-DMA mode, if a CRC error is detected during transfer, the ICRC and ABRT bits of the Error register are set at the end of the command.

6.1.28 Write-Multiple - C5H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|---------------------------|-----|---|-------|------------------|---|---|---|
| Command (7) | CAH or CBH | | | | | | | |
| C/D/H (6) | 1 | LBA | 1 | Drive | Head (LBA 27-24) | | | |
| Cyl High (5) | Cylinder High (LBA 23-16) | | | | | | | |
| Cyl Low (4) | Cylinder Low (LBA 15-8) | | | | | | | |
| Sec Num (3) | Sector Number (LBA 7-0) | | | | | | | |
| Sec Cnt (2) | Sector Count | | | | | | | |
| Feature (1) | X | | | | | | | |

Note: The current revision of the CompactFlash card can support up to a block count of 1 as indicated in the Identify Drive Command information.

This command is similar to the Write-Sectors command. The CompactFlash card sets BSY within 400 ns of accepting the command. Interrupts are not presented on each sector but on the transfer of a block which contains the number of sectors defined by Set-Multiple. Command execution is identical to the Write-Sectors operation except that the number of sectors defined by the Set-Multiple command is transferred without intervening interrupts

DRQ qualification of the transfer is required only at the start of the data block, not on each sector. The block count of sectors to be transferred without intervening interrupts is programmed by the Set-Multiple Mode command, which must be executed prior to the Write-Multiple command.

When the Write-Multiple command is issued, the Sector Count register contains the number of sectors (not the number of blocks or the block count) requested. If the number of requested sectors is not evenly divisible by the sector/block, as many full blocks as possible are transferred, followed by a final, partial block transfer. The partial block transfer is for n sectors, where: $n = \text{remainder}(\text{sector count}/\text{block count})$. If the Write-Multiple command is attempted before the Set-Multiple-Mode command has been executed or when Write-Multiple commands are disabled, the Write-Multiple operation will be rejected with an aborted command error.

Errors encountered during Write-Multiple commands are posted after the attempted writes of the block or partial block transferred. The Write command ends with the sector in error, even if it is in the middle of a block. Subsequent blocks are not transferred in the event of an error. Interrupts are generated when DRQ is set at the beginning of each block or partial block.

The Command Block registers contain the cylinder, head and sector number of the sector where the error occurred and the Sector Count register contains the residual number of sectors that need to be transferred for successful completion of the command, e.g. each block has 4 sectors, a request for 8 sectors is issued and an error occurs on the third sector. The Sector Count register contains 6 and the address is that of the third sector.

6.1.29 Write-Multiple-Without-Erase – CDH

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|---------------------------|-----|---|-------|------------------|---|---|---|
| Command (7) | CDH | | | | | | | |
| C/D/H (6) | 1 | LBA | 1 | Drive | Head (LBA 27-24) | | | |
| Cyl High (5) | Cylinder High (LBA 23-16) | | | | | | | |
| Cyl Low (4) | Cylinder Low (LBA 15-8) | | | | | | | |
| Sec Num (3) | Sector Number (LBA 7-0) | | | | | | | |
| Sec Cnt (2) | Sector Count | | | | | | | |
| Feature (1) | X | | | | | | | |

This command is similar to the Write-Multiple command with the exception that an implied Erase before Write operation is not performed. The sectors should be pre-erased with the Erase-Sector(s) command before this command is issued. If the sectors are not pre-erased with the Erase-Sector(s) command, a normal Write-Multiple operation will occur.

6.1.30 Write-Sector(s) – 30H or 31H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|---------------------------|-----|---|-------|------------------|---|---|---|
| Command (7) | 30H or 31H | | | | | | | |
| C/D/H (6) | X | LBA | X | Drive | Head (LBA 27-24) | | | |
| Cyl High (5) | Cylinder High (LBA 23-16) | | | | | | | |
| Cyl Low (4) | Cylinder Low (LBA 15-8) | | | | | | | |
| Sec Num (3) | Sector Number (LBA 7-0) | | | | | | | |
| Sec Cnt (2) | Sector Count | | | | | | | |
| Feature (1) | X | | | | | | | |

This command writes from 1 to 256 sectors as specified in the Sector Count register. A sector count of zero requests 256 sectors. The transfer begins at the sector specified in the Sector Number register.

When this command is accepted, the CompactFlash card sets BSY, then sets DRQ and clears BSY, then waits for the host to fill the sector buffer with the data to be written. No interrupt is generated to start the first host transfer operation. No data should be transferred by the host until BSY has been cleared by the host. For multiple sectors, after the first sector of data is in the buffer, BSY will be set and DRQ will be cleared. After the next buffer is ready for data, BSY is cleared, DRQ is set and an interrupt is generated. When the final sector of data is transferred, BSY is set and DRQ is cleared. It will remain in this state until the command is completed at which time BSY is cleared and an interrupt is generated. If an error occurs during a write of more than one sector, writing terminates at the sector where the error occurs. The Command Block registers contain the cylinder, head and sector number of the sector where the error occurred. The host may then read the command block to determine what error has occurred, and on which sector.

6.1.31 Write-Sector(s)-Without-Erase – 38H

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|---------------------------|-----|---|-------|------------------|---|---|---|
| Command (7) | 38H | | | | | | | |
| C/D/H (6) | X | LBA | X | Drive | Head (LBA 27-24) | | | |
| Cyl High (5) | Cylinder High (LBA 23-16) | | | | | | | |
| Cyl Low (4) | Cylinder Low (LBA 15-8) | | | | | | | |
| Sec Num (3) | Sector Number (LBA 7-0) | | | | | | | |
| Sec Cnt (2) | Sector Count | | | | | | | |
| Feature (1) | X | | | | | | | |

This command is similar to the Write-Sector(s) command with the exception that an implied Erase before Write operation is not performed. This command has the same protocol as the Write-Sector(s) command. The sectors should be pre-erased with the Erase-Sector(s) command before this command is issued. If the sector is not pre-erased with the Erase-Sector(s) command, a normal Write-Sector operation will occur.

6.1.32 Write-Verify – 3CH

| Bit -> | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|---------------------------|-----|---|-------|------------------|---|---|---|
| Command (7) | 3CH | | | | | | | |
| C/D/H (6) | X | LBA | X | Drive | Head (LBA 27-24) | | | |
| Cyl High (5) | Cylinder High (LBA 23-16) | | | | | | | |
| Cyl Low (4) | Cylinder Low (LBA 15-8) | | | | | | | |
| Sec Num (3) | Sector Number (LBA 7-0) | | | | | | | |
| Sec Cnt (2) | Sector Count | | | | | | | |
| Feature (1) | X | | | | | | | |

This command is similar to the Write-Sector(s) command, except each sector is verified immediately after being written. This command has the same protocol as the Write-Sector(s) command.

6.2 Error Posting

The following table summarizes the valid status and error values for the CompactFlash Card command set.

TABLE 6-1: Error and Status Register

| Command | Error Register | | | | | Status Register | | | | |
|-----------------------------|----------------|-----|------|------|------|-----------------|-----|-----|------|-----|
| | BBK | UNC | IDNF | ABRT | AMNF | RDY | DWF | DSC | CORR | ERR |
| Check-Power-Mode | | | | V | | V | V | V | | V |
| Execute-Drive-Diagnostic | | | | | | V | | V | | V |
| Format-Track | | | V | V | V | V | V | V | | V |
| Identify-Drive | | | | V | | V | V | V | | V |
| Idle | | | | V | | V | V | V | | V |
| Idle-Immediate | | | | V | | V | V | V | | V |
| Initialize-Drive-Parameters | | | | | | V | | V | | V |
| Read-Buffer | | | | V | | V | V | V | | V |
| Read DMA | V | V | V | V | V | V | V | V | V | V |
| Read-Multiple | V | V | V | V | V | V | V | V | V | V |
| Read-Long-Sector | V | | V | V | V | V | V | V | | V |
| Read-Sector(s) | V | V | V | V | V | V | V | V | V | V |
| Read-Verify-Sector(s) | V | V | V | V | V | V | V | V | V | V |
| Recalibrate | | | | V | | V | V | V | | V |
| Seek | | | V | V | | V | V | V | | V |
| Set-Features | | | | V | | V | V | V | | V |
| Set-Multiple-Mode | | | | V | | V | V | V | | V |
| Set-Sleep-Mode | | | | V | | V | V | V | | V |
| SMART | | | V | V | | V | V | V | | V |
| Standby | | | | V | | V | V | V | | V |
| Standby-Immediate | | | | V | | V | V | V | | V |
| Write-Buffer | | | | V | | V | V | V | | V |
| Write-Long-Sector | V | | V | V | V | V | V | V | | V |
| Write DMA | V | | V | V | V | V | V | V | | V |
| Write-Multiple | V | | V | V | V | V | V | V | | V |
| Write-Sector(s) | V | | V | V | V | V | V | V | | V |
| Write-Verify | V | | V | V | V | V | V | V | | V |
| Invalid-Command-Code | | | | V | | V | V | V | | V |

V = valid on this command

7. Electrical Specification

Caution: Absolute Maximum Stress Ratings – Applied conditions greater than those listed under “Absolute Maximum Stress Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these conditions or conditions greater than those defined in the operational sections of this data sheet is not implied. Exposure to absolute maximum stress rating conditions may affect device reliability.

Table 7-1: Operating range

| Range | Ambient Temperature | 3.3V | 5V |
|------------|---------------------|--------------|------------|
| Commercial | 0°C to +70°C | 3.135-3.465V | 4.75-5.25V |
| Industrial | -40°C to +85°C | | |

Table 7-2: Absolute maximum power pin stress ratings

| Parameter | Symbol | Conditions |
|--|----------|--|
| Input Power | V_{DD} | -0.3V min to 6.5V max -0.3V min to 4.0V max |
| Voltage on any flash media interface pin with respect to GND | V | -0.5V min to $V_{DD} + 0.5V$ max |

Table 7-3: Recommended system power-up timing

| Symbol | Parameter | Typical | Maximum | Units |
|------------------------|--|---------|---------|-------|
| TPU-READY ¹ | Host Power-up/Reset to Ready Operation | 200 | 1000 | ms |
| TPU-WRITE ¹ | Host Power-up/Reset to Write Operation | 200 | 1000 | ms |

1. This parameter is measured only for initial qualification and after a design or process change that could affect this parameter.

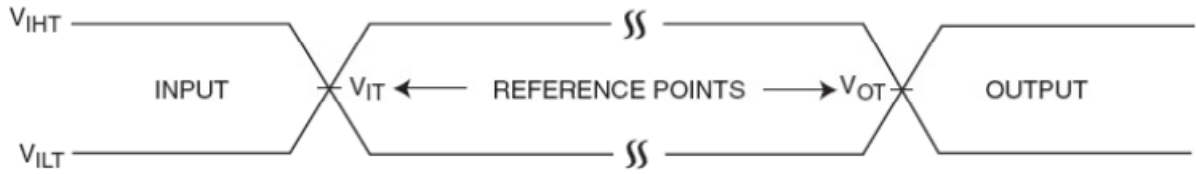
7.1 DC Characteristics

Table 7-4: DC Characteristics

| Symbol | Type | Parameter | Min | Max | Units | Conditions |
|------------------------|------|---|------|------|---------------|--|
| V_{IH1} V_{IL1} | I1 | Input Voltage | 2.0V | 0.8V | V | $V_{DDQ}=V_{DDQ} \text{ Max}$ $V_{DDQ}=V_{DDQ} \text{ Min}$ |
| I_{IL1} | I1Z | Input Leakage Current | -10 | 10 | μA | $V_{IN}=\text{GND to } V_{DDQ}$ $V_{DDQ}=V_{DDQ} \text{ Max}$ |
| I_{U1} | I1U | Input Pull-Up Current | -110 | -1 | μA | $V_{OUT}=\text{GND,}$ $V_{DDQ}=V_{DDQ} \text{ Max}$ |
| V_{T+2} V_{T-2} | I2 | Input Voltage Schmitt Trigger | 0.8 | 2.0 | V | $V_{DDQ}=V_{DDQ} \text{ Max}$ $V_{DDQ}=V_{DDQ} \text{ Min}$ |
| I_{IL2} | I2Z | Input Leakage Current | -10 | 10 | μA | $V_{IN}=\text{GND to } V_{DDQ}$ $V_{DDQ}=V_{DDQ} \text{ Max}$ |
| I_{U2} | I2U | Input Pull-Up Current | -110 | -1 | μA | $V_{OUT}=\text{GND,}$ $V_{DDQ}=V_{DDQ} \text{ Max}$ |
| V_{OH1} V_{OL1} | O1 | Output Voltage | 2.4 | 0.4 | V | $I_{OH1}=I_{OH1} \text{ Min}$ $I_{OL1}=I_{OL1} \text{ Max}$ |
| I_{OH1} | | Output Current | -4 | | mA | $V_{DDQ}=V_{DDQ} \text{ Min}$ |
| I_{OL1} | | Output Current | | 4 | mA | $V_{DDQ}=V_{DDQ} \text{ Min}$ |
| V_{OH2} V_{OL2} | O2 | Output Voltage | 2.4 | 0.4 | V | $I_{OH2}=I_{OH2} \text{ Min}$ $I_{OL2}=I_{OL2} \text{ Max}$ |
| I_{OH2} | | Output Current | -6 | | mA | $V_{DDQ}=3.135\text{V}-3.465\text{V}$ |
| I_{OL2} | | Output Current | | 6 | mA | $V_{DDQ}=3.135\text{V}-3.465\text{V}$ |
| I_{OH2} | | Output Current | -8 | | mA | $V_{DDQ}=4.5\text{V}-5.5\text{V}$ |
| I_{OL2} | | Output Current | | 8 | mA | $V_{DDQ}=4.5\text{V}-5.5\text{V}$ |
| V_{OH6} V_{OL6} | O6 | Output Voltage for DASP# pin | 2.4 | 0.4 | V | $I_{OH6}=I_{OH6} \text{ Min}$ $I_{OL6}=I_{OL6} \text{ Max}$ |
| I_{OH6} | | Output Current for DASP# pin | -3 | | mA | $V_{DDQ}=3.135\text{V}-3.465\text{V}$ |
| I_{OL6} | | Output Current for DASP# pin | | 8 | mA | $V_{DDQ}=3.135\text{V}-3.465\text{V}$ |
| I_{OH6} | | Output Current for DASP# pin | -3 | | mA | $V_{DDQ}=4.5\text{V}-5.5\text{V}$ |
| I_{OL6} | | Output Current for DASP# pin | | 12 | mA | $V_{DDQ}=4.5\text{V}-5.5\text{V}$ |
| $I_{DD}^{1,2}$ | PWR | Power supply current ($T_a = 0^\circ\text{C to } +70^\circ\text{C}$) | | 50 | mA | $V_{DD}=V_{DD} \text{ Max}$ $V_{DDQ}=V_{DDQ} \text{ Max}$ |
| $I_{DD}^{1,2}$ | PWR | Power supply current ($T_a = -40^\circ\text{C to } +85^\circ\text{C}$) | | 75 | mA | $V_{DD}=V_{DD} \text{ Max}$ $V_{DDQ}=V_{DDQ} \text{ Max}$ |
| I_{SP} | PWR | Sleep/Standby/Idle current ($T_a = 0^\circ\text{C to } +70^\circ\text{C}$) | | 75 | μA | $V_{DD}=V_{DD} \text{ Max}$ $V_{DDQ}=V_{DDQ} \text{ Max}$ |
| I_{SP} | PWR | Sleep/Standby/Idle current ($T_a = -40^\circ\text{C to } +85^\circ\text{C}$) | | 200 | μA | $V_{DD}=V_{DD} \text{ Max}$ $V_{DDQ}=V_{DDQ} \text{ Max}$ |

1. Sequential data transfer for 1 sector read data from host interface and write data to media.
2. This parameter is measured only for initial qualification and after a design or process change that could affect this parameter.

7.2 AC Characteristics



AC test inputs are driven at V_{IHT} (0.9 V_{DD}) for a logic "1" and V_{ILT} (0.1 V_{DD}) for a logic "0". Measurement reference points for inputs and outputs are V_{IT} (0.5 V_{DD}) and V_{OT} (0.5 V_{DD}). Input rise and fall times (10% \leftrightarrow 90%) are <10 ns.

Note: V_{IT} - INPUT Test
 V_{OT} - VOUTPUT Test
 V_{IHT} - INPUT HIGH Test
 V_{ILT} - INPUT LOW Test

7.2.1 Attribute Memory Read Timing Specification

The Attribute Memory access time is defined as 100 ns. Detailed timing specifications are shown in the table below.

Table 7-5 Attribute Memory Read Timing Specification

| Speed Version | Symbol | IEEE Symbol | 100 ns | | |
|--------------------------------|---------------|-------------|------------------|------------------|-------|
| | | | Min ¹ | Min ¹ | Units |
| Read Cycle Time | $T_{C(R)}$ | tAVAV | 100 | | ns |
| Address Access Time | $T_{A(A)}$ | tAVQV | | 100 | ns |
| Card Enable Access Time | $T_{A(CE)}$ | tELQV | | 100 | ns |
| Output Enable Access Time | $T_{A(OE)}$ | tGLQV | | 50 | ns |
| Output Disable Time from CE# | $T_{DIS(CE)}$ | tEHQZ | | 50 | ns |
| Output Disable Time from OE# | $T_{DIS(OE)}$ | tGHQZ | | 50 | ns |
| Address Setup Time | $T_{SU(A)}$ | tAVGL | 10 | | ns |
| Output Enable Time from CE# | $T_{EN(CE)}$ | tELQNZ | 5 | | ns |
| Output Enable Time from OE# | $T_{EN(OE)}$ | tGLQNZ | 5 | | ns |
| Data Valid from Address Change | $T_{V(A)}$ | tAXQZ | 0 | | ns |

1. D_{OUT} signifies data provided by the Compact Flash card to the system. The CE# signal or both the OE# signal and the WE# signal must be de-asserted between consecutive cycle operations. All AC specifications are guaranteed by design.

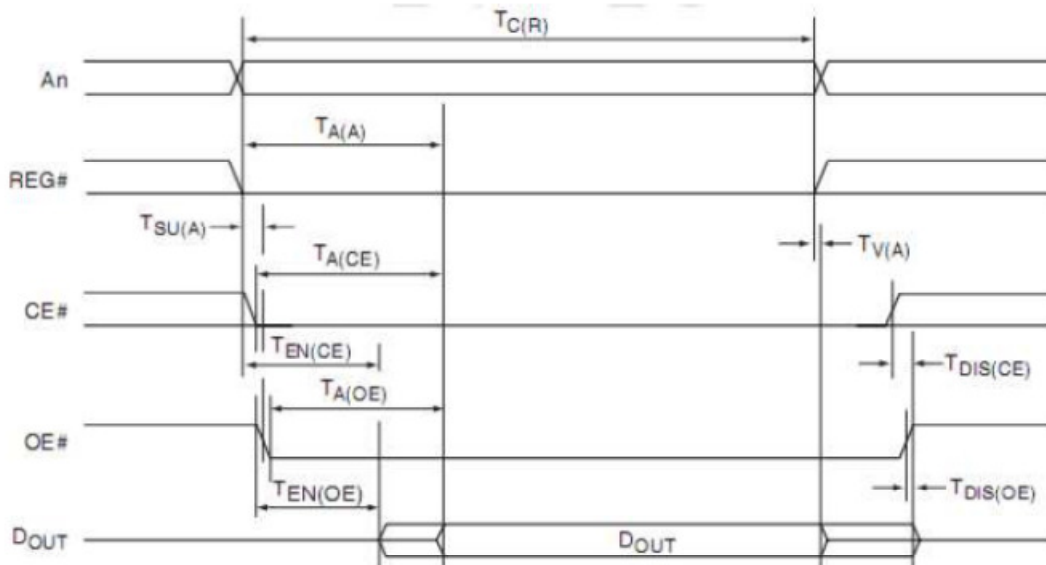


Figure 7-2: Attribute Memory Read Timing Diagram

1365 F03.0

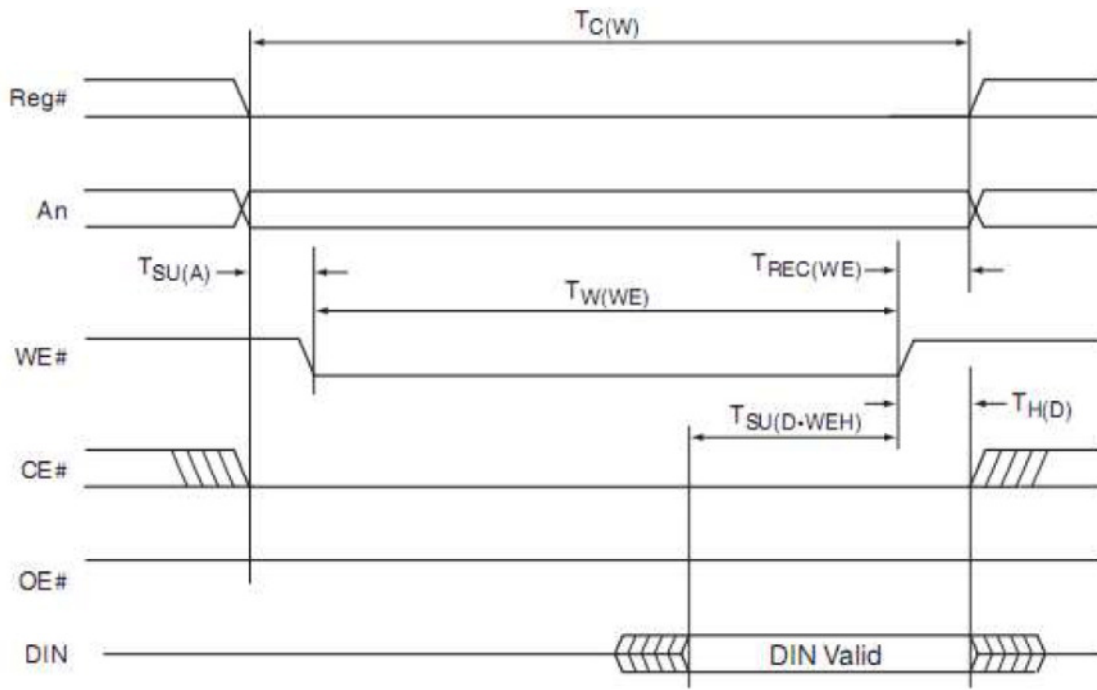
7.2.2 Configuration Register (Attribute Memory) Write Specification

The card configuration write access time is defined as 100 ns. Detailed timing specifications are shown in the table below.

Table 7-6 Configuration Register (Attribute Memory) Write Timing

| Speed Version | | | 100 ns | | |
|------------------------|------------------|-------------|------------------|------------------|-------|
| Item | Symbol | IEEE Symbol | Min ¹ | Min ¹ | Units |
| Write Cycle Time | $T_{C(W)}$ | tAVAV | 100 | | ns |
| Write Pulse Width | $T_{W(WE)}$ | tWLWH | 60 | | ns |
| Address Setup Time | $T_{SU(A)}$ | tAVWL | 10 | | ns |
| Write Recover Time | $T_{REC(WE)}$ | tWMAX | 15 | | ns |
| Data Setup Time for WE | $T_{SU(DWE\#H)}$ | tDVWH | 40 | | ns |
| Data Hold Time | $T_{H(D)}$ | tWMDX | 15 | | ns |

1. D_{IN} signifies data provided by the system to the Compact Flash card. All AC specifications are guaranteed by design.



1355 F04.0

Figure 7-3: Configuration Register (Attribute Memory) Write Timing Diagram

7.2.3 Common Memory Read Timing Specification

Table 7-7 Common Memory Read Timing

| Item | Symbol | IEEE Symbol | Min ¹ | Min ¹ | Units |
|-----------------------------|---------------|-------------|------------------|------------------|-------|
| Output Enable Access Time | $T_{A(OE)}$ | tGLQV | | 50 | ns |
| Output Disable Time from OE | $T_{DIS(OE)}$ | tGHQZ | | 50 | ns |
| Address Setup Time | $T_{SU(A)}$ | tAVGL | 10 | | ns |
| Address Hold Time | $T_{REC(WE)}$ | tGHAX | 15 | | ns |
| CE Setup before OE | $T_{SU(CE)}$ | tELGL | 0 | | ns |
| CE Hold following OE | $T_{H(CE)}$ | tGHEH | 15 | | ns |

1. All AC specifications are guaranteed by design.

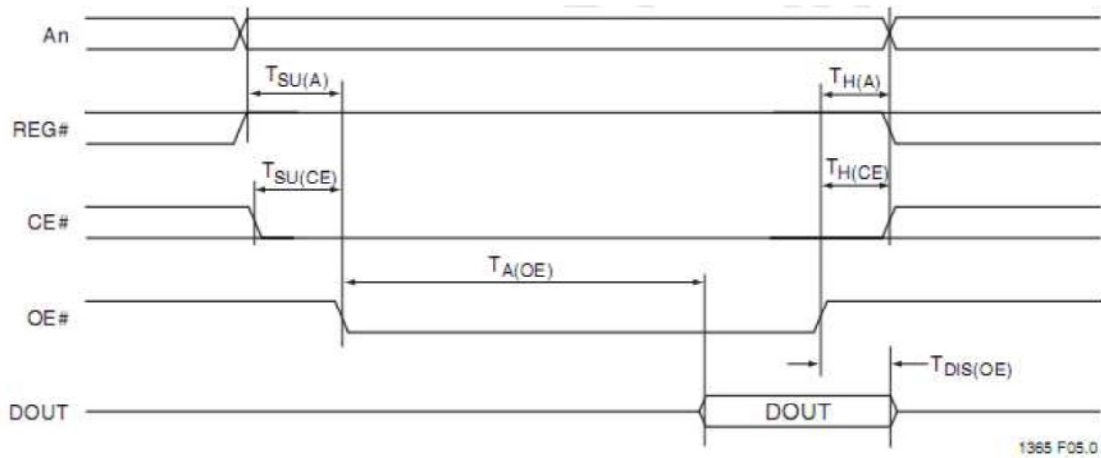


Figure 7-4: Common Memory Read Timing Diagram

7.2.4 Common Memory Write Timing Specification

Table 7-8 Common Memory Write Timing

| Item | Symbol | IEEE Symbol | Min ¹ | Min ¹ | Units |
|------------------------|------------------|-------------|------------------|------------------|-------|
| Data Setup before WE | $T_{SU(DWE\#H)}$ | tDVWH | 40 | | ns |
| Data Hold following WE | $T_{H(D)}$ | tWMDX | 15 | | ns |
| WE Pulse Width | $T_{W(WE)}$ | tWLWH | 60 | | ns |
| Address Setup Time | $T_{SU(A)}$ | tAVWL | 10 | | ns |
| CE Setup before WE | $T_{SU(CE)}$ | tELWL | 0 | | ns |
| Write Recovery Time | $T_{REC(WE)}$ | tWMAX | 15 | | ns |
| Address Hold Time | $T_{H(A)}$ | tGHAX | 15 | | ns |
| CE Hold following WE | $T_{H(CE)}$ | tGHEH | 15 | | ns |

1. All AC specifications are guaranteed by design.

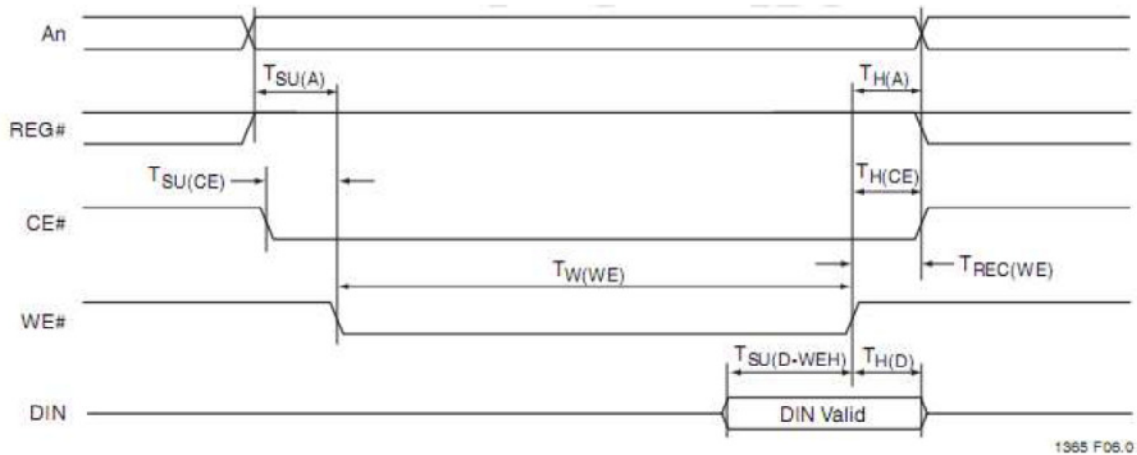


Figure 7-5: Common Memory Write Timing Diagram

7.2.5 I/O Input (Read) Timing Specification

Table 7-9 I/O Read Timing

| Item | Symbol | IEEE Symbol | Min ¹ | Min ¹ | Units |
|-----------------------------------|----------------------|-------------|------------------|------------------|-------|
| Data Delay after IORD | $T_{D(IORD)}$ | tIGLQV | | 100 | ns |
| Data Hold following IORD | $T_{H(IORD)}$ | tIGHQX | 0 | | ns |
| IORD Width Time | $T_{W(IORD)}$ | tIGLIGH | 165 | | ns |
| Address Setup before IORD | $T_{SUA(IORD)}$ | tAVIGL | 70 | | ns |
| Address Hold following IORD | $T_{HA(IORD)}$ | tIGHAX | 20 | | ns |
| CE Setup before IORD | $T_{SUCE(IORD)}$ | tELIGL | 5 | | ns |
| CE Hold following IORD | $T_{HCE(IORD)}$ | tIGHEH | 20 | | ns |
| REG Setup before IORD | $T_{SUREG(IORD)}$ | tRGLIGL | 5 | | ns |
| REG Hold following IORD | $T_{HREG(IORD)}$ | tIGHRGH | 0 | | ns |
| INPACK Delay Falling from IORD | $T_{DFINPACK(IORD)}$ | tIGLIAI | 0 | 45 | ns |
| INPACK Delay Rising from IORD | $T_{DRINPACK(IORD)}$ | tIGHIAH | | 45 | ns |
| IOIS16 Delay Falling from Address | $T_{DFIOIS16(ADR)}$ | tAVISL | | 35 | ns |
| IOIS16 Delay Rising from Address | $T_{DRIOIS16(ADR)}$ | tAVISH | | 35 | ns |

1. All AC specifications are guaranteed by design.
 Note: The maximum load on -INPACK and IOIS16# is 1 LSTTL with 50pF total load.

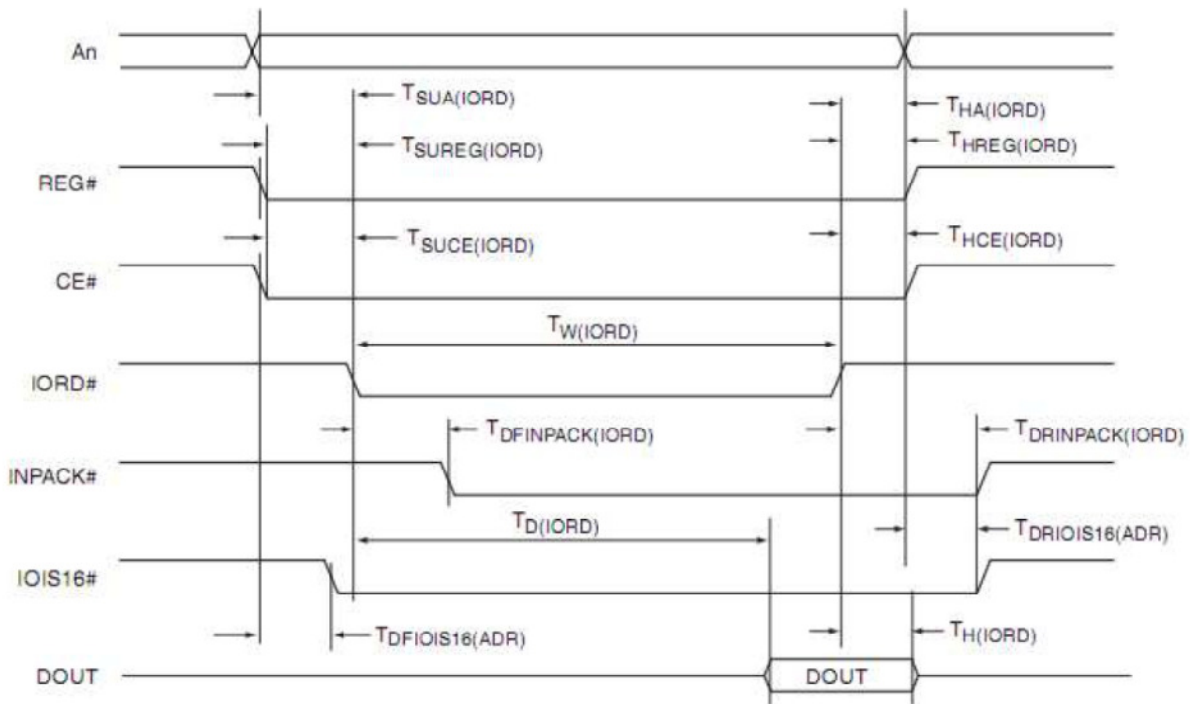


Figure 7-6: I/O Read Timing Diagram

7.2.6 I/O Output (Write) Timing Specification

Table 7-10 I/O Write Timing

| Item | Symbol | IEEE Symbol | Min ¹ | Min ¹ | Units |
|-----------------------------------|---------------------|-------------|------------------|------------------|-------|
| Data Setup before IOWR | $T_{SU(IOWR)}$ | tDVIWH | 60 | | ns |
| Data Hold following IOWR | $T_{H(IOWR)}$ | tIWHDX | 30 | | ns |
| IOWR Width Time | $T_{W(IOWR)}$ | tWLIWH | 165 | | ns |
| Address Setup before IOWR | $T_{SUA(IOWR)}$ | tAVIWL | 70 | | ns |
| Address Hold following IOWR | $T_{HA(IOWR)}$ | tIWHAX | 20 | | ns |
| CE Setup before IOWR | $T_{SUCE(IOWR)}$ | tELIWL | 5 | | ns |
| CE Hold following IOWR | $T_{HCE(IOWR)}$ | tIWHHEH | 20 | | ns |
| REG Setup before IOWR | $T_{SUREG(IOWR)}$ | tRGLIWL | 5 | | ns |
| REG Hold following IOWR | $T_{HREG(IOWR)}$ | tIWHRGH | 0 | | ns |
| IOIS16 Delay Falling from Address | $T_{DFIOIS16(ADR)}$ | tAVISL | | 35 | ns |
| IOIS16 Delay Rising from Address | $T_{DRIOIS16(ADR)}$ | tAVISH | | 35 | ns |

1. All AC specifications are guaranteed by design.

Note: The maximum load on -INPACK and IOIS16# is 1 LSTTL with 50pF total load.

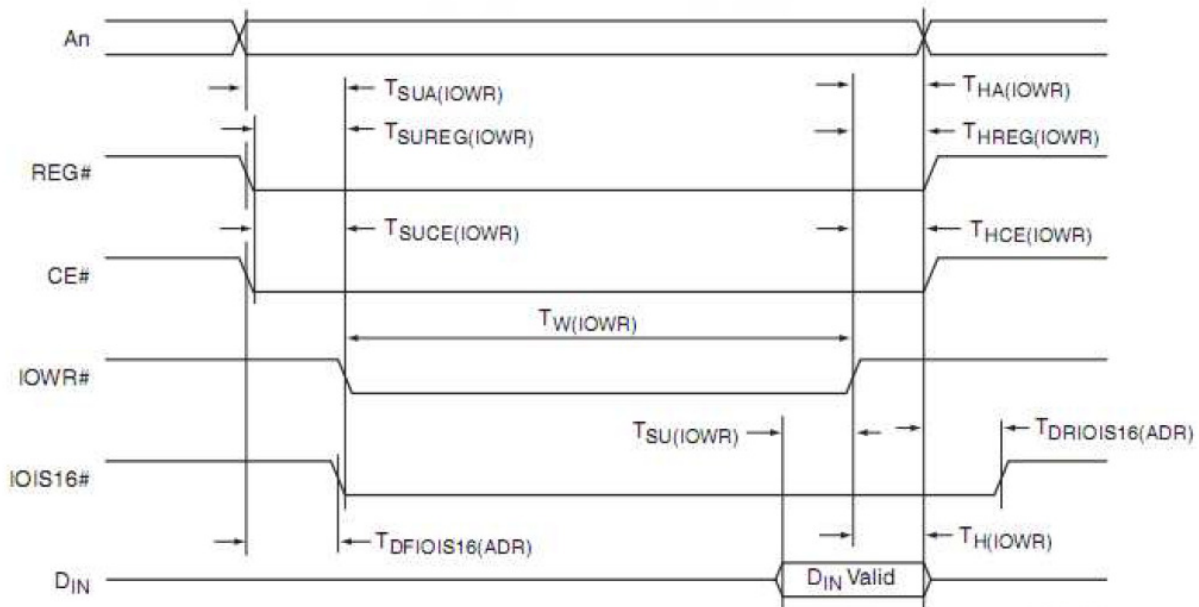


Figure 7-7: I/O Write Timing Diagram

7.2.7 Ultra DMA Mode Data Transfer Input/Output (Read/Write) Timing

Table 7-11 Ultra DMA Data Burst Timing Specifications¹

| Name | Descriptions | Mode 4 | | Unit | Measurement Location ² |
|----------------------|--|--------|-----|------|-----------------------------------|
| | | Min | Max | | |
| T _{2CYCTYP} | Typical sustained average two cycle time | 60 | | ns | Sender |
| T _{CYC} | Cycle time allowing for asymmetry and clock variations (from STROBE edge to STROBE edge) | 25 | | ns | Note ³ |
| T _{2CYC} | Two cycle time allowing for clock variations (from rising edge to next rising edge or from falling edge to next falling edge of STROBE) | 57 | | ns | Sender |
| T _{DS} | Data setup time at recipient (from data valid until STROBE edge) ^{4,5} | 5.0 | | ns | Recipient |
| T _{DH} | Data hold time at Recipient (from STROBE edge until data becomes invalid) ^{1,2} | 5.0 | | ns | Recipient |
| T _{DVS} | Data valid setup time for Sender (from data valid until STROBE edge) ⁵ | 6.0 | | ns | Sender |
| T _{DVH} | Data valid hold time at Sender (from STROBE edge until data becomes invalid) ³ | 6.0 | | ns | Sender |
| T _{CS} | CRC word setup time at device ¹ | 5.0 | | ns | Device |
| T _{CH} | CRC word hold time at device ¹ | 5.0 | | ns | Device |
| T _{CVS} | CRC word valid setup time at host (from CRC valid until DMACK negation) ³ | 6.7 | | ns | Host |
| T _{CVH} | CRC word valid hold time at Sender (from DMACK negation until CRC becomes invalid) ³ | 6.2 | | ns | Host |
| T _{ZFS} | Time from STROBE output released-to-driving until the first transition of critical timing | 0 | | ns | Device |
| T _{DZFS} | Time from data output released-to-driving until the first transition of critical timing | 6.7 | | ns | Sender |
| T _{FS} | First STROBE time (for device to first negate DSTROBE from STOP during a data in burst) | | 120 | ns | Device |
| T _{LI} | Limited interlock time ⁷ | 0 | 100 | ns | Note ⁸ |
| T _{MLI} | Interlock time with minimum ⁸ | 20 | | ns | Host |
| T _{ULI} | Unlimited interlock time ⁸ | 0 | | ns | Host |
| T _{AZ} | Maximum time allowed for output drivers to release (from asserted to negated) | | 10 | ns | Note ⁵ |
| T _{ZAH} | Minimum delay time required for output | 20 | | ns | Host |
| T _{ZAD} | Drivers to assert or negate (from released) | 0 | | ns | Device |
| T _{ENV} | Envelope time (from DMACK# to STOP and HDMARDY# during data in burst initiation and from DMACK to STOP during data our burst initiation) | 20 | 55 | ns | Host |
| T _{RFS} | Ready-to-final STROBE time (no STROBE edge are sent this long after negation of DMARDY) | | 60 | ns | Sender |
| T _{RP} | Ready-to-pause time (Recipient waits to pause until after negating DMARDY) | 100 | | ns | Recipient |
| T _{IORDYZ} | Maximum time before releasing IORDY | | 20 | ns | Device |
| T _{ZIORDY} | Minimum time before driving IORDY ¹⁰ | 0 | | ns | Device |
| T _{ACK} | | 20 | | ns | Host |
| T _{SS} | | 50 | | ns | Sender |

CompactFlash Card

FMS-CFxxxxE3NR-XXXXQ



4. All timing measurement switching points (low-to-high and high-to-low) are taken at 1.5V.
5. All signal transitions for a timing parameter are measured at the connector specified in the measurement location column. For example, in the case of TRFS, both STROBE and DMARDY Transitions are measured at the Sender connector.
6. The parameter TCYC is measured at the recipient's connector farthest from the Sender.
7. 80-Conductor cabling is required in order to meet sup (TDS, TCS) and hold (TDH, TCH) times in modes greater than two.
8. The parameters TDS and TDH for Mode 5 are defined for a Recipient at the end of the cable only in a configuration with a single device located at the end of the cable. This could result in the minimum values for TDS and TDH for mode 5 at the middle connector being 3.0 and 3.9 ns respectively.
9. Timing for TDVS, TDVH, TCVS, and TCVH are met for lumped capacitive loads of 15 and 50 pf at the connector where the Data and STROBE signals have the same capacitive load value. Due to reflections on the cable, these timing measurements are not valid in a normally functioning system.
10. The parameters TUI, TMLI, and TLI indicate Sender-to-Recipient or Recipient-to-Sender interlocks. For example, one agent (either Sender or Recipient) is waiting for the other agent to respond with a signal before proceeding; TUI is an unlimited interlock that has no maximum time value, TMLI is a limited time-out that has a defined minimum, and TLI is a limited time-out that has a defined maximum.
11. The parameter TLI is measured at the connector of the Sender or Recipient that is responding to an incoming transition from the Recipient or Sender respectively. Both the incoming signal and the outgoing response are measured at the same connector.
12. The parameter TAZ is measured at the connector of the Sender or Recipient that is driving the bus but must release the bus that allow for a bus turnaround.
13. For all modes the parameter TZIORDY may be greater than TENV because the host has a pull-on IORDY giving it a known state when released.

Table 7-12 Ultra DMA Sender and Recipient IC Timing Specifications¹

| Name | Descriptions | Mode 4 | | Unit |
|-------------|--|--------|-----|------|
| | | Min | Max | |
| T_{DSIC} | Recipient IC data setup time (from data valid until STROBE edge) ² | 4.8 | | ns |
| T_{DHIC} | Recipient IC data hold time (from STROBE edge until data becomes invalid) ¹ | 4.8 | | ns |
| T_{DVSIC} | Sender IC data valid setup time (from data valid until STROBE edge) ³ | 9.5 | | ns |
| T_{DVHIC} | | 9.0 | | ns |

1. All timing measurement switching point (low-to-high and high-to-low)
2. The correct data value is captured by the Recipient given input data with a slew rate of 0.4 V/ns rising and falling and the input STROBE with a slew rate of 0.4 V/ns rising and falling at TDSIC and TDHIC timing (as measured through 1.5 V).
3. The parameters TDVSIC and TDVHIC are met for lumped capacitive loads of 15 and 40 pF at the IC where all signals have the same capacitive load value. Noise that may couple onto the output signals from external sources has not been included in these values.

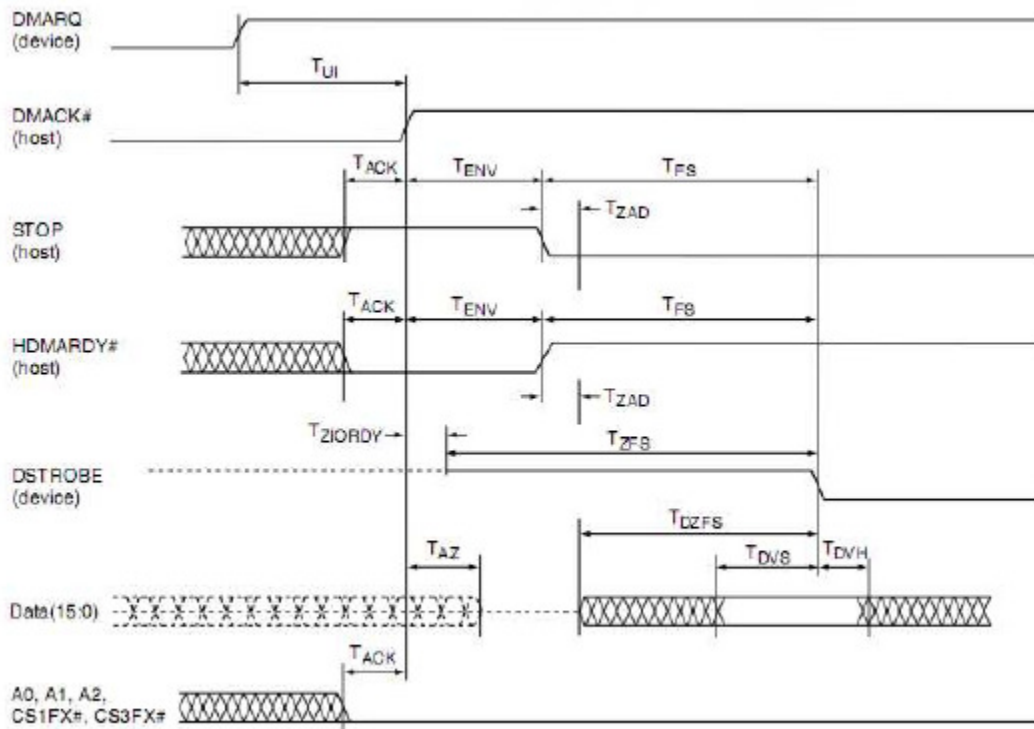


Figure 7-8: Initiating an Ultra DMA Data-In Burst

Notes:

1. The definitions for the DIOW:-:STOP, DIOR:-:HDMARDY:-:HSTROBE, and IORDY:DDRARDY:-: DSTROBE signal lines are not in effect until DMARQ and DMACK are asserted.

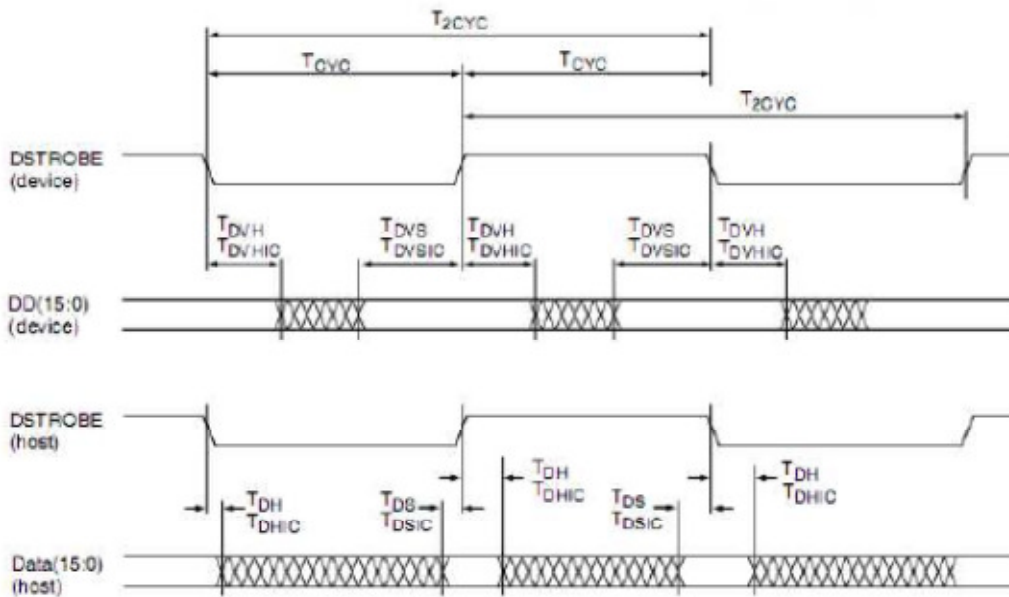


Figure 7-9: Sustained Ultra DMA Data-In Burst

Notes:

1. DD(15:0) and DSTROBE signals are shown at both the host and the device to emphasize that cable settling time as well as cable propagation delay will not allow the data signals to be considered stable at the host until sometime after they are driven by the device.

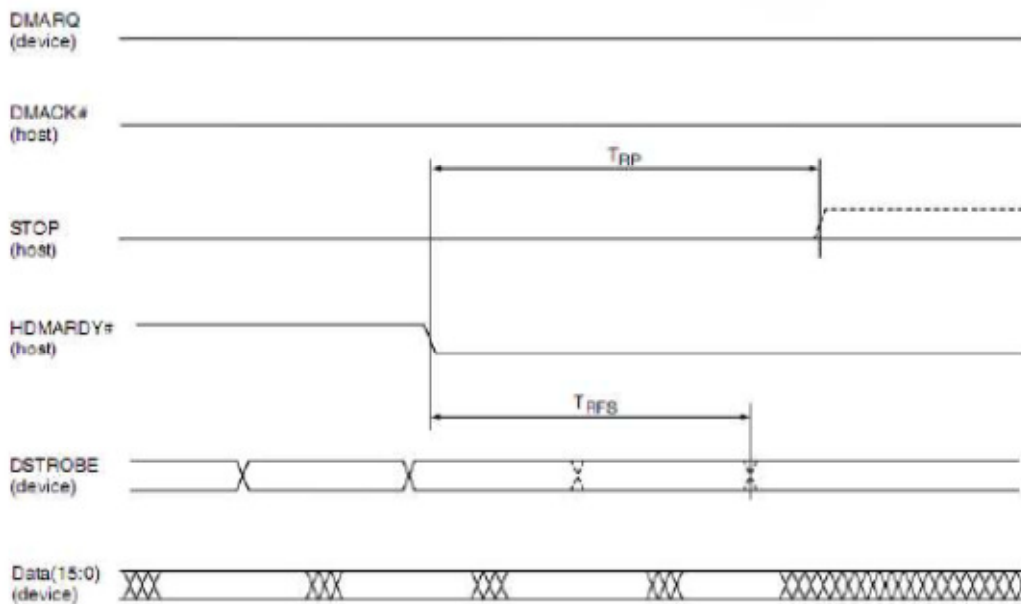


Figure 7-10: Sustained Ultra DMA Data-In Burst

Notes:

1. The host may assert STOP to request termination of the Ultra DMA burst no sooner than TRP after HDMARDY# is negated.
2. After negating HDMARDY#, the host may receive zero, one, two, or three more data words from the device.

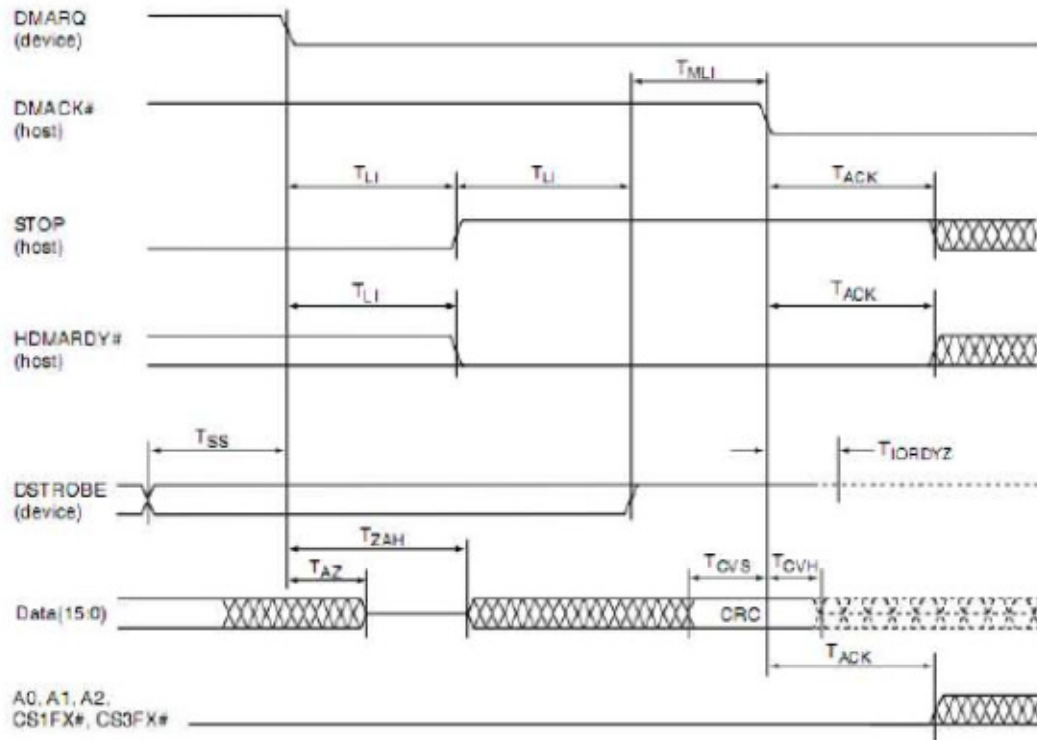


Figure 7-11: Device Terminating and Ultra DMA Data-In Burst

Notes:

1. The definitions for the STOP, HDMARDY, and DSTROBE signal lines are no longer in effect after DMARQ and DMACK are negated.

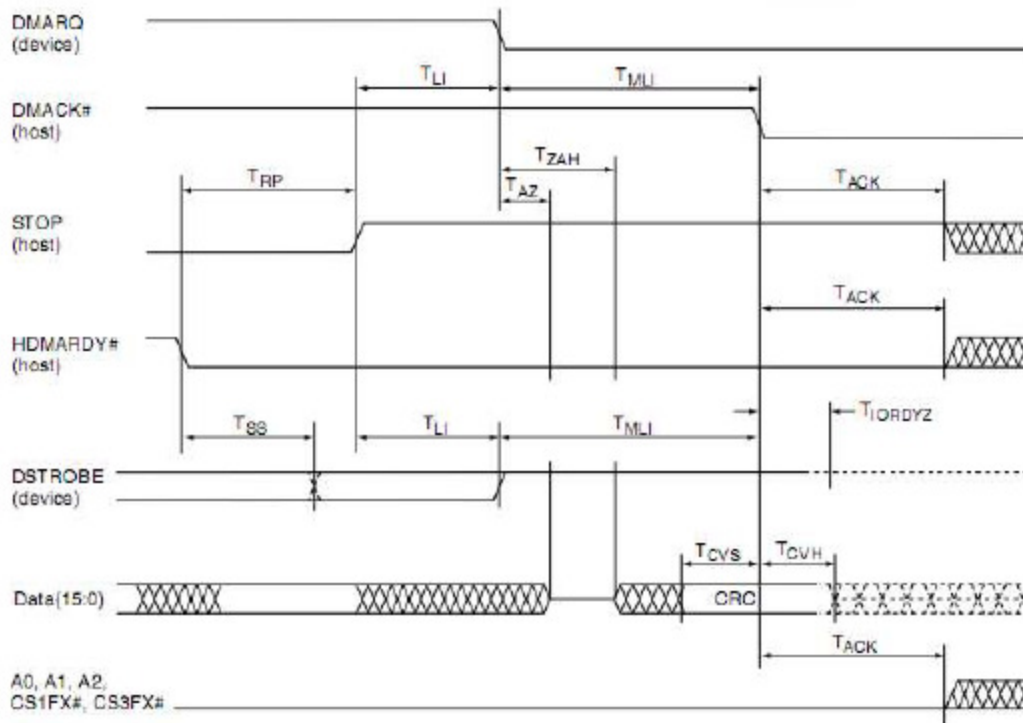


Figure 7-12: Host Terminating and Ultra DMA Data-In Burst

Notes:

1. The definitions for the STOP, HDMARDY, and DSTROBE signal lines are no longer in effect after DMARQ and DMACK are negated.

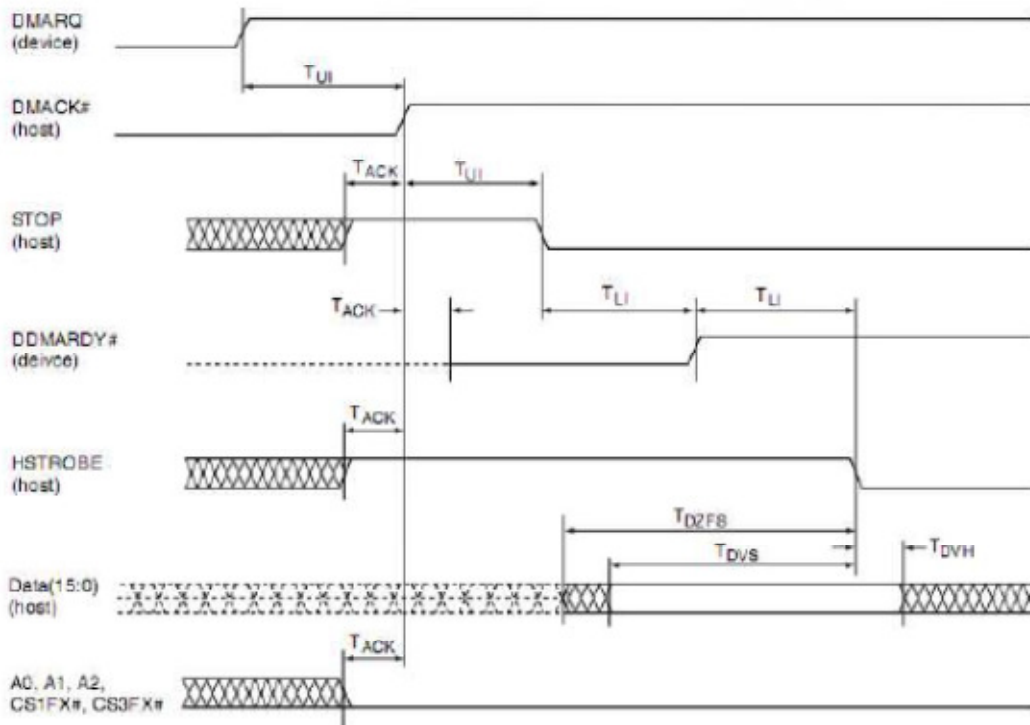


Figure 7-13: Initiating an Ultra DMA Data-Out Burst

Notes:

1. The definitions for the STOP, DDMARDY, and HSTROBE signal lines are no longer in effect after DMARQ and DMACK are negated.

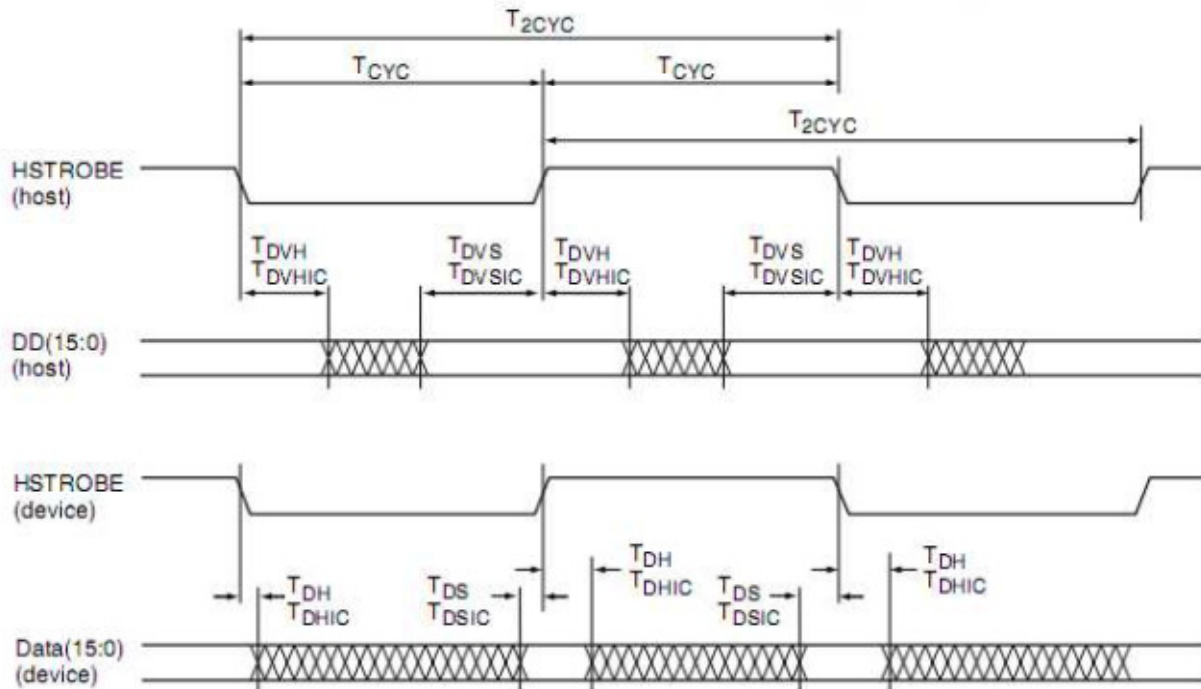


Figure 7-14: Sustained Ultra DMA Data-Out Burst

Notes:

1. DD(15:0) and HSTROBE signals are shown at both the host and the device to emphasize that cable settling time as well as cable propagation delay will not allow the data signals to be considered stable at the host until some time after they are driven by the host.

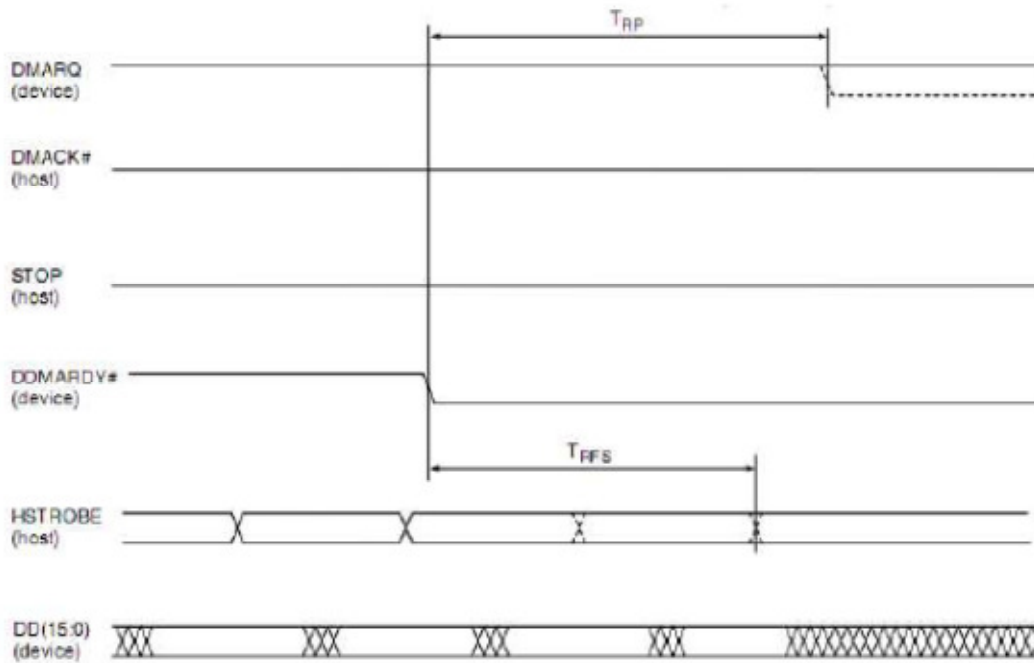


Figure 7-15: Device Pausing and Ultra DMA Data-Out Burst

Notes:

1. The host may negate DMARQ to request termination of the Ultra DMA burst no sooner than TRP after DDMARDY# is negated.
2. After negating DDMARDY#, the host may receive zero, one, two, or three more data words from the host.

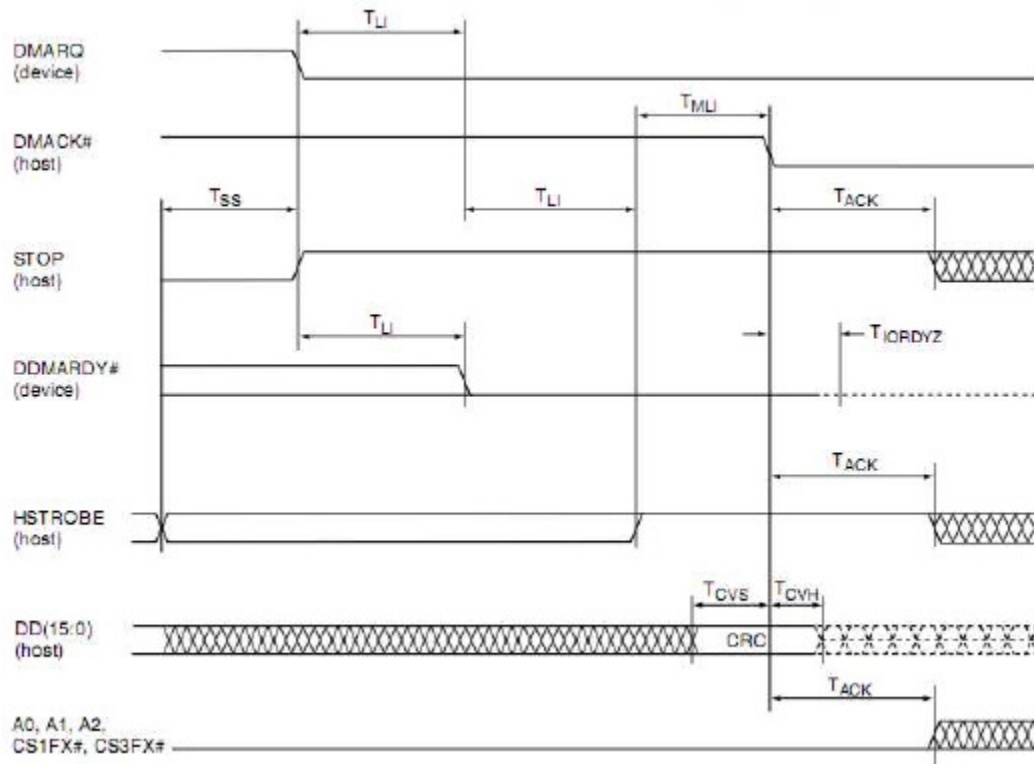


Figure 7-16: Host Terminating and Ultra DMA Data-Out Burst

Notes:

1. The definitions for the STOP, DDMARDY, and HSTROBE signal lines are no longer in effect after DMARQ and DMACK are negated.

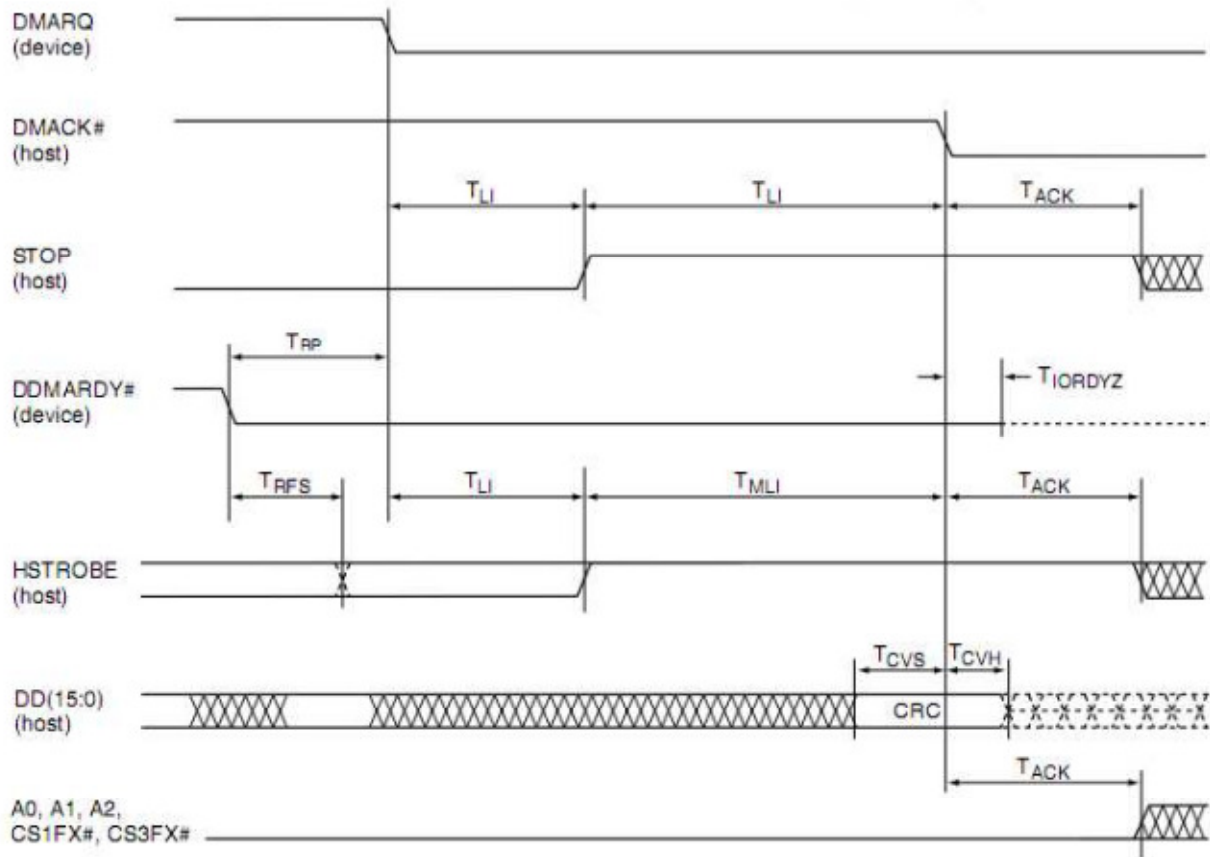


Figure 7-17: Device Terminating and Ultra DMA Data-Out Burst

Notes:

1. The definitions for the STOP, DDMARDY, and HSTROBE signal lines are no longer in effect after DMARQ and DMACK are negated.

8. Physical Characteristics

8.1 Dimensions

TABLE 8-1: Type I CFC physical specification

| | |
|-----------------------------------|--------------------------------------|
| Length: | 36.40 +/- 0.15mm (1.433+/- 0.06 in.) |
| Width: | 42.80 +/- 0.10mm (1.685+/- 0.04 in.) |
| Thickness (Including Label Area): | 3.3mm+/-0.10mm (0.130+/-0.04in.) |

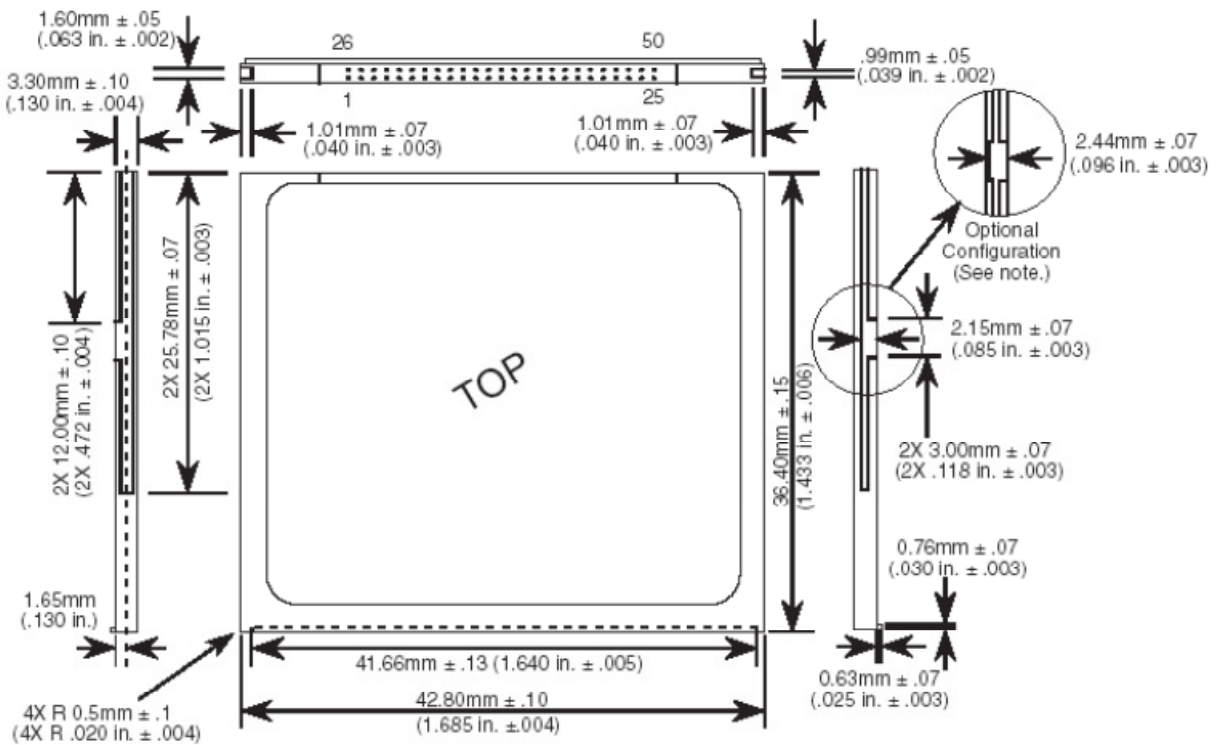
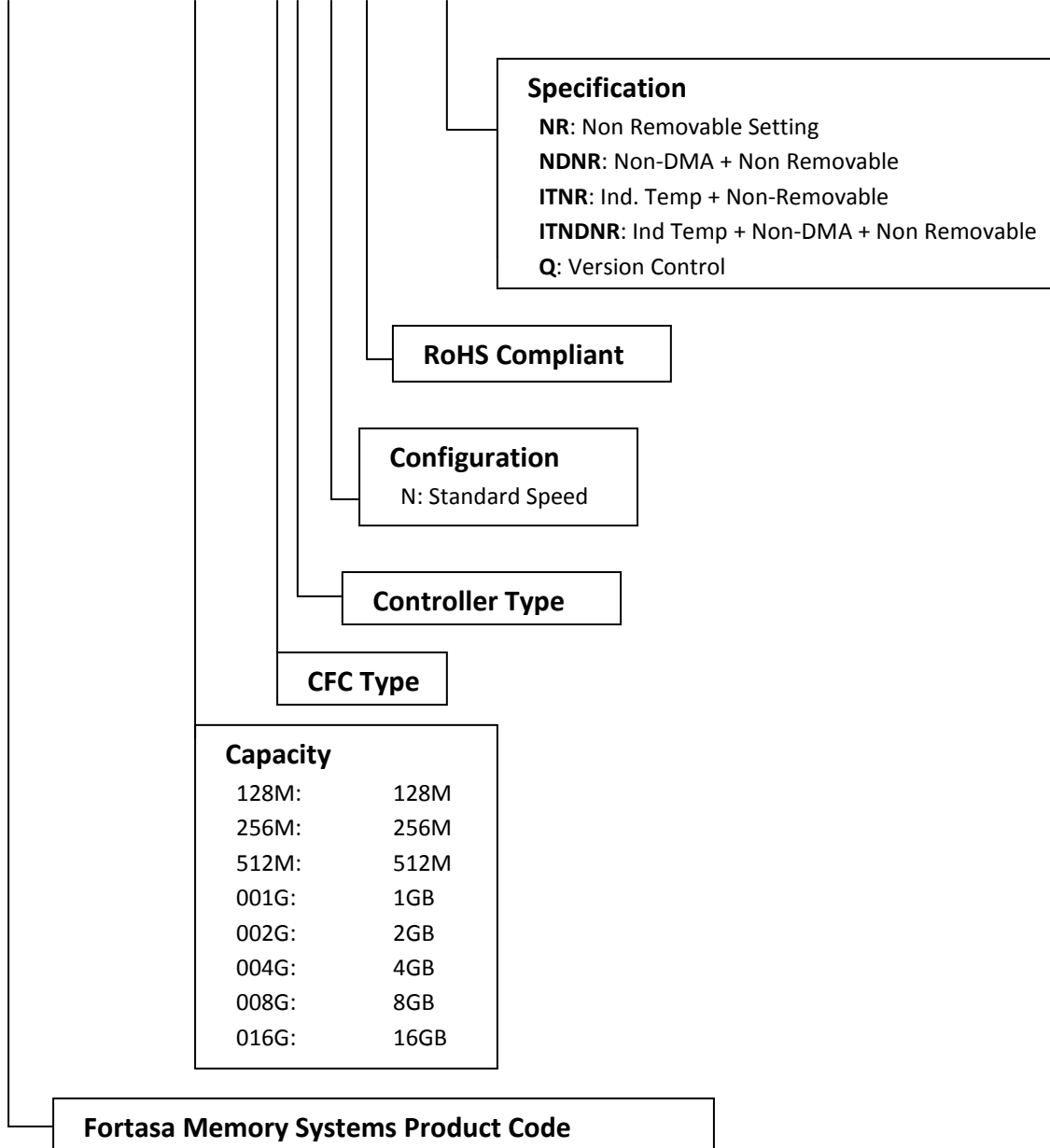


FIGURE 8-1: Physical dimension

9. Product Ordering Information

9.1 Product Code Designations

FMS – C F x x x x E 3 N R – XXXXQ



9.2 Valid Combinations

9.2.1 Standard Temperature

Non-Removable Configuration

| Standard Speed | |
|----------------|--------------------|
| Capacity | Model Number |
| 128M | FMS-CF128ME3NR-NRQ |
| 256M | FMS-CF256ME3NR-NRQ |
| 512M | FMS-CF512ME3NR-NRQ |
| 1GB | FMS-CF001GE3NR-NRQ |
| 2GB | FMS-CF002GE3NR-NRQ |
| 4GB | FMS-CF004GE3NR-NRQ |
| 8GB | FMS-CF008GE3NR-NRQ |
| 16GB | FMS-CF016GE3NR-NRQ |

Non-DMA and Non-Removable Configuration

| Standard Speed | |
|----------------|----------------------|
| Capacity | Model Number |
| 128M | FMS-CF128ME3NR-NDNRQ |
| 256M | FMS-CF256ME3NR-NDNRQ |
| 512M | FMS-CF512ME3NR-NDNRQ |
| 1GB | FMS-CF001GE3NR-NDNRQ |
| 2GB | FMS-CF002GE3NR-NDNRQ |
| 4GB | FMS-CF004GE3NR-NDNRQ |
| 8GB | FMS-CF008GE3NR-NDNRQ |
| 16GB | FMS-CF016GE3NR-NDNRQ |

9.2.2 Industrial Temperature

Non-Removable Configuration

| Standard Speed | |
|----------------|---------------------|
| Capacity | Model Number |
| 128M | FMS-CF128ME3NR-INRQ |
| 256M | FMS-CF256ME3NR-INRQ |
| 512M | FMS-CF512ME3NR-INRQ |
| 1GB | FMS-CF001GE3NR-INRQ |
| 2GB | FMS-CF002GE3NR-INRQ |
| 4GB | FMS-CF004GE3NR-INRQ |
| 8GB | FMS-CF008GE3NR-INRQ |
| 16GB | FMS-CF016GE3NR-INRQ |

Non-DMA and Non-Removable Configuration

| Standard Speed | |
|----------------|-----------------------|
| Capacity | Model Number |
| 128M | FMS-CF128ME3NR-INDNRQ |
| 256M | FMS-CF256ME3NR-INDNRQ |
| 512M | FMS-CF512ME3NR-INDNRQ |
| 1GB | FMS-CF001GE3NR-INDNRQ |
| 2GB | FMS-CF002GE3NR-INDNRQ |
| 4GB | FMS-CF004GE3NR-INDNRQ |
| 8GB | FMS-CF008GE3NR-INDNRQ |
| 16GB | FMS-CF016GE3NR-INDNRQ |

10. Revision History

| Revision | Date | Description | Comments |
|----------|-----------|---|----------|
| 1.0 | 5/19/2011 | Initial Release | |
| 1.1 | 8/11/2013 | Updated performance and product ordering information due to change in NAND flash use Added endurance TBW section to replace MTBF | |